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Dynamic Programming Driven Memetic Search for the Steiner Tree Problem with Revenues, Budget and Hop Constraints - Online Supplement

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1. Worst Case Complexity Analysis

We provide here a worst case complexity analysis of the proposed memetic algorithm. The algorithm consists of several main ingredients, including a pre-processing procedure, a probabilistic constructive procedure, a dynamic programming based neighborhood search (NS) procedure, a crossover operator associated with a pool updating strategy, whose computational complexities are respectively bounded as follows.

1. *Pre-processing procedure* (15): The pre-processing procedure is used to calculate and store all the possible values of $L(i, j, l)$, $i, j \in V, r_j > 0, 1 \leq l \leq H$ before the search (which would be fetched directly during the search, instead of calculating them repeatedly). Using a dynamic programming procedure (20), these computations can be achieved within a time of $O(|V| \times |PV| \times H) \leq O(|V|^2 \times H)$, where PV denotes the set containing all the profitable vertices (with $r_j > 0$) of graph G .

2. *Probabilistic constructive procedure* (15): Using the needed $L(i, j, l)$ values provided by the pre-processing step, the computations at each construction step can be finished within a time of $O(|V| \times |PV| + |V| \times H)$. Since at most $|PV|$ steps are needed to complete the

construction procedure, the total time for constructing a saturated BHS-tree is bounded within $O(|V| \times |PV|^2 + |PV| \times |V| \times H) \leq O(|V|^3 + |V|^2 \times H)$.

3. *Neighborhood search (NS) procedure*: Due to the possibility of special cases and the unknown number of NS iterations before termination, it is difficult to give an exact computational complexity of the NS procedure, thus we just provide a worst case analysis as follows. At first, at the beginning of each iteration of NS, we should re-execute the dynamic programming procedure of Eq. (2), whose complexity is bounded within $O(|V_{urp}| \times W_{max}) \leq O(|PV| \times B) \leq O(|V| \times B)$. Then, up to $O(|lv(T)|^2) \leq O(|PV|^2) \leq O(|V|^2)$ possible neighboring solutions should be examined by the estimation criterion (each one needs $O(H)$ time to get the available budget after deletion and $O(1)$ time to check if the examined neighboring solution could be directly discarded), among which only the hopeful ones identified by the estimation criterion should be actually generated. As explained in subsection 3.2.4, with the aid of the dynamic driven estimation criterion, in most cases only one or very few neighboring solutions should be actually generated. However, in the worst case (i.e., special case 1 occurs for every neighboring solution), it is possible that all the $O(|lv(T)|^2) \leq O(|V|^2)$ neighboring solutions should be actually generated. Now we discuss the time needed for actually generating a neighboring solution. At first, for preparation, we should store (and restore afterwards) the incumbent solution, both within $O(|V|)$ time. Then, the path deletion can be done within $O(H)$ time. After that, up to $|V_{urp}|$ new paths may be inserted, each one with $O(|V|)$ time to re-calculate a new hop-constrained shortest path between the chosen vertex for connection and the solution after path deletion, and up to $O(|V| \times H)$ time to insert the renewed hop-constrained shortest path, using the pre-calculated values of $L(i, j, l)$. Thus the time complexity of actually generating a neighboring solution is bounded within $O(|V|) + O(H) + O(|V_{urp}|) \times O(|V|) + O(|V_{urp}|) \times O(|V| \times H) \leq O(|V|^2 \times H)$. Based on the above information, the complexity of each iteration of NS is bounded within $O(|V| \times B) + O(|lv(T)|^2) \times O(H) + O(|lv(T)|^2) \times O(|V|^2 \times H) \leq O(|V| \times B + |V|^4 \times H)$. Given that it is difficult to exactly estimate the number of iterations before termination. Let I denote the maximum possible number of NS iterations (I is typically but unnecessarily in proportion to $|V|$), then the overall complexity of the NS procedure is bounded by $I \times O(|V| \times B + |V|^4 \times H)$.

4. *Crossover operator*: At first, the shared backbone of any two solutions could be identified (first step of the crossover operator) within a complexity of $O(|PV| \times H) \leq O(|V| \times H)$.

Subsequently, to complete the backbone and obtain a saturated BHS-tree, a complexity bounded by the probabilistic constructive procedure is needed, i.e., $O(|V|^3 + |V|^2 \times H)$, as analyzed above. Thus, the crossover operator can be achieved within $O(|V| \times H) + O(|V|^3 + |V|^2 \times H) = O(|V|^3 + |V|^2 \times H)$ time.

5. *Pool updating strategy*: Basically, the distance between any two solutions can be calculated within $O(|V|)$ time. Based on this, for the sake of a quick updating, we maintain in a $Q \times Q$ matrix the distances between any pair of solutions belonging to *Pop* (requiring a complexity of $O(|V| \times Q^2)$ for initialization). With this distance matrix, given a new offspring solution T^0 and the population *Pop* containing Q solutions, the goodness score of each solution of *Pop* can be calculated within $O(|V| + Q)$ time, and the goodness score of T^0 can be calculated within $O(|V| \times Q)$ time, meaning that the worst (with the lowest goodness score) solution of $Pop \cup \{T^0\}$ can be identified within a complexity of $O(Q) \times O(|V| + Q) + O(|V| \times Q) = O(|V| \times Q + Q^2)$. Finally, after replacing T^0 with some other existing solution, the distances matrix is updated within a complexity of $O(|V| \times Q)$. Overall, updating the solutions pool with a new offspring is done within a time of $O(|V| \times Q + Q^2) + O(|V| \times Q) = O(|V| \times Q + Q^2)$ (excluding the complexity needed for distances matrix initialization).

To summarize, the complexity of each round of the NS procedure followed by crossover and pool updating is bounded within $I \times O(|V| \times B + |V|^4 \times H) + O(|V|^3 + |V|^2 \times H) + O(|V| \times Q + Q^2) = O(I \times |V| \times B + I \times |V|^4 \times H + |V| \times Q + Q^2)$. Give that it is difficult to estimate the number of such rounds needed for a run of the memetic algorithm. If denote the maximum number of such rounds by G (G is typically but unnecessarily in proportion to M), the overall complexity (including the pre-processing procedure, the solutions pool initialization, as well as the distance matrix initialization) of each independent run of memetic is bounded within $O(|V|^2 \times H) + Q \times O(|V|^3 + |V|^2 \times H) + O(|V| \times Q^2) + G \times O(I \times |V| \times B + I \times |V|^4 \times H + |V| \times Q + Q^2)$. Again, we would like to point out this is only a worst case analysis which serves as a theoretical upper bound of computational complexity, being much higher than the actually needed computational efforts in most cases.

2. Supplementary results and additional comparisons

Table 1 Results of the memetic algorithm with a reduced termination criterion using $M = 50$ (Memetic(50)) on the 56 most challenging instances of group G4, in comparison with previous fast heuristics D&R and TS(2000)

Instance			D&R		TS(2000)		Memetic(50)		Instance			D&R		TS(2000)		Memetic(50)	
<i>Graph</i>	<i>b</i>	<i>H</i>	R^{best}	$t(s)$	R^{best}	$t(s)$	R^{best}	$t(s)$	<i>Graph</i>	<i>b</i>	<i>H</i>	R^{best}	$t(s)$	R^{best}	$t(s)$	R^{best}	$t(s)$
C8_10	20	5	208	1.32	≤228	14.2	228	3.02	C8_10	50	5	104	0.12	≤116	13.6	116	2.14
C8_10	20	15	303	9.51	≤308	42.0	324	6.86	C8_10	50	15	152	1.91	≤161	41.6	171	5.16
C8_10	20	25	311	16.23	≤310	65.6	329	8.87	C8_10	50	25	151	3.19	≤160	63.7	172	7.96
C8_100	20	5	2261	1.28	≤2365	13.5	2365	4.03	C8_100	50	5	1151	0.23	≤1204	13.5	1216	2.61
C8_100	20	15	3269	9.24	≤3237	43.1	3370	7.13	C8_100	50	15	1696	1.88	≤1675	41.8	1750	5.71
C8_100	20	25	3310	16.87	≤3337	66.8	3416	9.74	C8_100	50	25	1735	1.79	≤1742	64.3	1792	8.02
C9_10	20	5	274	2.26	≤279	16.0	302	5.60	C9_10	50	5	143	0.26	≤145	16.1	149	3.67
C9_10	20	15	354	11.35	≤349	42.4	372	9.01	C9_10	50	15	172	2.36	≤165	39.3	184	8.11
C9_10	20	25	353	9.45	≤353	63.0	375	12.81	C9_10	50	25	168	3.70	≤167	59.1	185	11.66
C9_100	20	5	2864	2.24	≤2933	16.4	3112	6.31	C9_100	50	5	1514	0.50	≤1509	15.8	1563	3.88
C9_100	20	15	3642	11.15	≤3588	41.5	3853	10.59	C9_100	50	15	1675	2.13	≤1742	38.6	1878	8.13
C9_100	20	25	3602	17.26	≤3644	62.1	3878	14.08	C9_100	50	25	1674	3.35	≤1745	59.4	1905	12.52
C10_10	20	5	341	2.07	≤371	14.4	385	7.73	C10_10	50	5	156	0.39	≤173	13.9	184	5.71
C10_10	20	15	505	13.07	≤505	41.4	540	19.66	C10_10	50	15	211	2.54	≤221	40.4	247	15.95
C10_10	20	25	482	19.86	≤501	67.2	550	27.51	C10_10	50	25	219	3.83	≤218	62.9	250	23.49
C10_100	20	5	3530	1.88	≤3811	15.5	4055	8.89	C10_100	50	5	1513	0.32	≤1836	14.0	1937	6.27
C10_100	20	15	5163	13.30	≤5227	45.5	5621	21.35	C10_100	50	15	2415	2.88	≤2365	39.7	2550	15.69
C10_100	20	25	5287	22.97	≤5286	64.9	5703	29.11	C10_100	50	25	2472	4.66	≤2432	63.8	2586	24.18
C13_10	100	5	242	2.67	≤243	26.6	251	3.40	C13_10	100	15	303	12.57	≤296	72.8	311	6.22
C13_10	100	25	302	22.19	≤298	107.3	311	8.62	C13_100	100	5	2507	2.48	≤2526	25.9	2599	3.90
C13_100	100	15	3064	11.64	≤3029	70.4	3244	6.95	C13_100	100	25	3064	22.72	≤3057	109.8	3251	9.41
C14_10	100	5	344	5.33	339	26.8	368	5.20	C14_10	100	15	377	17.72	≤370	71.4	392	9.32
C14_10	100	25	377	28.02	369	101.8	391	12.73	C14_100	100	5	3485	5.02	≤3416	26.3	3843	6.61
C14_100	100	15	3846	17.32	≤3872	71.5	4110	11.50	C14_100	100	25	3846	27.43	≤3856	102.2	4107	14.13
C15_10	20	5	1174	79.48	≤1192	28.9	1218	30.08	C15_10	100	5	401	4.94	≤427	26.2	450	10.55
C15_10	100	15	515	23.48	≤501	71.0	558	18.11	C15_10	100	25	520	38.60	510	107.7	559	25.74
C15_100	20	5	12078	83.31	≤12198	28.5	12353	40.13	C15_100	100	5	4180	5.17	≤4358	27.1	4741	11.11
C15_100	100	15	5355	24.04	≤5177	70.8	5776	21.98	C15_100	100	25	5393	41.07	5243	106.7	5792	27.41

Table 2 Comparison between Memetic/DP and the memetic algorithm for solving the 56 most challenging cases of group G4

Instance			Memetic/DP			Memetic			Instance			Memetic/DP			Memetic		
<i>Graph</i>	<i>b</i>	<i>H</i>	R^{best}	R^{avg}	$t(s)$	R^{best}	R^{avg}	$t(s)$	<i>Graph</i>	<i>b</i>	<i>H</i>	R^{best}	R^{avg}	$t(s)$	R^{best}	R^{avg}	$t(s)$
C8_10	20	5	230	229.4	446.53	230	230.0	19.06	C8_10	50	5	116	116.0	69.99	116	116.0	10.80
C8_10	20	15	328	326.4	539.48	330	327.8	42.37	C8_10	50	15	171	168.1	70.07	171	168.5	23.03
C8_10	20	25	331	329.3	548.89	330	329.0	35.60	C8_10	50	25	172	171.6	83.17	172	171.6	31.50
C8_100	20	5	2380	2367.7	525.52	2380	2374.0	24.37	C8_100	50	5	1216	1212.0	92.18	1216	1216.0	12.30
C8_100	20	15	3412	3384.6	636.87	3418	3407.6	47.39	C8_100	50	15	1774	1757.7	109.59	1774	1759.6	26.46
C8_100	20	25	3429	3413.9	620.59	3443	3426.5	48.16	C8_100	50	25	1792	1784.8	103.36	1792	1784.2	33.34
C9_10	20	5	301	298.4	599.20	302	299.3	29.31	C9_10	50	5	149	148.9	73.95	149	149.0	16.04
C9_10	20	15	374	372.5	406.81	376	372.4	42.45	C9_10	50	15	184	182.1	107.67	183	180.8	34.77
C9_10	20	25	380	374.9	444.21	377	374.7	54.65	C9_10	50	25	186	185.8	108.47	186	184.8	43.77
C9_100	20	5	3112	3088.2	845.56	3112	3092.8	38.16	C9_100	50	5	1563	1563.0	86.07	1563	1563.0	17.57
C9_100	20	15	3875	3860.6	820.02	3873	3854.5	56.49	C9_100	50	15	1899	1871.5	121.28	1879	1863.5	36.32
C9_100	20	25	3912	3887.6	621.32	3906	3881.4	71.83	C9_100	50	25	1918	1906.9	158.94	1909	1898.6	50.11
C10_10	20	5	388	387.3	1009.09	388	387.4	57.24	C10_10	50	5	185	184.3	142.94	185	184.1	26.66
C10_10	20	15	551	544.9	1557.19	553	545.2	113.51	C10_10	50	15	247	247.0	175.81	247	247.0	61.70
C10_10	20	25	558	553.7	1587.71	561	555.4	133.69	C10_10	50	25	256	250.6	210.59	254	249.6	78.51
C10_100	20	5	4088	4067.3	1402.74	4069	4047.9	67.42	C10_100	50	5	1940	1939.4	149.69	1940	1939.3	34.83
C10_100	20	15	5682	5620.9	2133.47	5686	5620.0	130.25	C10_100	50	15	2566	2551.6	233.34	2601	2552.1	71.46
C10_100	20	25	5838	5738.1	1914.11	5773	5694.6	139.72	C10_100	50	25	2586	2579.5	260.60	2632	2576.1	92.41
C13_10	100	5	254	251.8	380.54	253	251.1	22.97	C13_10	100	15	312	310.5	266.70	316	312.0	33.71
C13_10	100	25	314	311.9	342.20	314	311.6	37.38	C13_100	100	5	2609	2590.4	450.91	2622	2593.0	29.87
C13_100	100	15	3253	3242.3	395.94	3255	3242.7	41.05	C13_100	100	25	3257	3245.6	460.48	3260	3241.2	42.62
C14_10	100	5	368	365.5	810.57	370	366.0	29.95	C14_10	100	15	396	393.4	889.66	398	394.7	55.08
C14_10	100	25	396	393.2	928.70	397	393.8	53.99	C14_100	100	5	3843	3827.6	1032.97	3847	3823.7	36.42
C14_100	100	15	4156	4127.2	1155.39	4172	4150.2	72.46	C14_100	100	25	4161	4126.2	1199.43	4150	4121.6	76.56
C15_10	20	5	1218	1214.7	7214.87	1221	1218.2	188.94	C15_10	100	5	458	453.6	1834.20	462	456.0	71.42
C15_10	100	15	559	557.4	941.18	558	557.5	92.59	C15_10	100	25	558	558.0	1131.41	558	556.4	99.20
C15_100	20	5	12370	12341.1	7218.16	12392	12366.5	359.13	C15_100	100	5	4779	4668.5	2051.51	4807	4758.0	97.01
C15_100	100	15	5807	5786.7	1384.34	5807	5793.8	109.24	C15_100	100	25	5807	5788.1	1481.98	5822	5795.7	127.45

Table 3 Comparison between ILS and the memetic algorithm for solving the 56 most challenging cases of group G4

Instance			ILS			Memetic			Instance			ILS			Memetic		
<i>Graph</i>	<i>b</i>	<i>H</i>	R^{best}	R^{avg}	$t(s)$	R^{best}	R^{avg}	$t(s)$	<i>Graph</i>	<i>b</i>	<i>H</i>	R^{best}	R^{avg}	$t(s)$	R^{best}	R^{avg}	$t(s)$
C8_10	20	5	230	228.4	15.64	230	230.0	19.06	C8_10	50	5	116	115.8	8.89	116	116.0	10.80
C8_10	20	15	327	325.1	25.67	330	327.8	42.37	C8_10	50	15	168	167.5	12.77	171	168.5	23.03
C8_10	20	25	330	327.8	28.60	330	329.0	35.60	C8_10	50	25	172	171.2	15.36	172	171.6	31.50
C8_100	20	5	2373	2349.1	20.29	2380	2374.0	24.37	C8_100	50	5	1216	1206.0	10.67	1216	1216.0	12.30
C8_100	20	15	3414	3375.4	34.18	3418	3407.6	47.39	C8_100	50	15	1764	1750.9	16.28	1774	1759.6	26.46
C8_100	20	25	3414	3403.4	33.54	3443	3426.5	48.16	C8_100	50	25	1792	1783.4	18.10	1792	1784.2	33.34
C9_10	20	5	301	297.1	27.39	302	299.3	29.31	C9_10	50	5	149	149.0	11.88	149	149.0	16.04
C9_10	20	15	377	373.4	30.88	376	372.4	42.45	C9_10	50	15	184	182.7	21.34	183	180.8	34.77
C9_10	20	25	379	376.5	34.32	377	374.7	54.65	C9_10	50	25	186	184.1	24.66	186	184.8	43.77
C9_100	20	5	3112	3089.3	36.65	3112	3092.8	38.16	C9_100	50	5	1563	1563.0	11.52	1563	1563.0	17.57
C9_100	20	15	3918	3882.3	34.91	3873	3854.5	56.49	C9_100	50	15	1888	1875.0	21.44	1879	1863.5	36.32
C9_100	20	25	3932	3889.2	41.76	3906	3881.4	71.83	C9_100	50	25	1895	1885.8	27.73	1909	1898.6	50.11
C10_10	20	5	386	384.9	41.42	388	387.4	57.24	C10_10	50	5	184	184.0	17.65	185	184.1	26.66
C10_10	20	15	545	540.7	58.81	553	545.2	113.51	C10_10	50	15	247	247.0	30.27	247	247.0	61.70
C10_10	20	25	553	547.4	75.24	561	555.4	133.69	C10_10	50	25	251	249.3	43.51	254	249.6	78.51
C10_100	20	5	4079	4043.7	62.36	4069	4047.9	67.42	C10_100	50	5	1939	1938.8	22.59	1940	1939.3	34.83
C10_100	20	15	5662	5584.1	83.03	5686	5620.0	130.25	C10_100	50	15	2550	2542.1	37.42	2601	2552.1	71.46
C10_100	20	25	5743	5658.9	96.00	5773	5694.6	139.72	C10_100	50	25	2587	2569.9	50.27	2632	2576.1	92.41
C13_10	100	5	252	249.7	19.11	253	251.1	22.97	C13_10	100	15	313	311.1	18.62	316	312.0	33.71
C13_10	100	25	313	311.3	20.85	314	311.6	37.38	C13_100	100	5	2609	2584.6	26.62	2622	2593.0	29.87
C13_100	100	15	3243	3238.2	28.45	3255	3242.7	41.05	C13_100	100	25	3260	3241.7	31.29	3260	3241.2	42.62
C14_10	100	5	368	365.6	29.62	370	366.0	29.95	C14_10	100	15	396	391.2	36.06	398	394.7	55.08
C14_10	100	25	393	391.4	37.37	397	393.8	53.99	C14_100	100	5	3811	3803.3	44.91	3847	3823.7	36.42
C14_100	100	15	4151	4108.1	54.37	4172	4150.2	72.46	C14_100	100	25	4136	4103.8	49.72	4150	4121.6	76.56
C15_10	20	5	1210	1206.5	292.71	1221	1218.2	188.94	C15_10	100	5	457	452.4	45.15	462	456.0	71.42
C15_10	100	15	559	556.9	59.97	558	557.5	92.59	C15_10	100	25	558	557.3	64.92	558	556.4	99.20
C15_100	20	5	12266	12253.1	378.12	12392	12366.5	359.13	C15_100	100	5	4741	4723.8	68.79	4807	4758.0	97.01
C15_100	100	15	5792	5773.3	67.00	5807	5793.8	109.24	C15_100	100	25	5792	5779.9	70.66	5822	5795.7	127.45