Iterated variable neighborhood search for the capacitated clustering problem

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Abstract

The NP-hard capacitated clustering problem (CCP) is a general model with a number of relevant applications. This paper proposes a highly effective iterated variable neighborhood search (IVNS) algorithm for solving the problem. IVNS combines an extended variable neighborhood descent method and a randomized shake procedure to explore effectively the search space. The computational results obtained on three sets of 133 benchmarks reveal that the proposed algorithm competes favorably with the state-of-the-art algorithms in the literature both in terms of solution quality and computational efficiency. In particular, IVNS discovers an improved best known result (new lower bounds) for 28 out of 83 most popular instances, while matching the current best known results for the remaining 55 instances. Several essential components of the proposed algorithm are investigated to understand their impacts on the performance of algorithm.

Keywords: Capacitated clustering; grouping problem; variable neighborhood search; heuristics.

1 1 Introduction

- Given a weighted undirect graph G = (V, E, C, w), where $V = \{v_1, v_2, \dots, v_n\}$
- 3 is the set of n nodes, E is the set of its edges, $C = \{c_{ij} : \{v_i, v_j\} \in E\}$
- 4 represents the set of edge weights, and $w = \{w_i \geq 0 : v_i \in V\}$ is the set
- of node weights, the capacitated clustering problem (CCP) is to partition the

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- node set V into a fixed number p ($p \le n$ is given) of disjoint clusters (or groups) such that the sum of node weights of each cluster lies in a given interval [L, U] while maximizing the sum of the edge weights whose two associated endpoints locate in the same cluster. In some related literature like [9,23], an edge weight $c_{ij} \in C$ is also called the benefit of the edge $\{v_i, v_j\}$, while L and U are called the lower and upper capacity limits of a cluster.
- Formally, the CCP can be expressed as the following quadratic program with binary variables X_{ig} taking the value of 1 if node v_i is in cluster g and 0 otherwise [9,23]:

(CCP) Maximize
$$\sum_{g=1}^{p} \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} c_{ij} X_{ig} X_{jg}$$
 (1)

Subject to
$$\sum_{g=1}^{p} X_{ig} = 1, i = 1, 2, \dots, n$$
 (2)

$$L \le \sum_{i=1}^{n} w_i X_{ig} \le U, g = 1, 2, \dots, p$$
 (3)

$$X_{ig} \in \{0, 1\}, i = 1, 2, \dots, n; g = 1, 2, \dots, p$$
 (4)

$$c_{ij} = 0, \forall \{v_i, v_j\} \notin E \tag{5}$$

where the set of constraints (2) guarantees that each node is located in exactly one cluster (or group) and the set of constraints (3) forces the sum of node weights of each cluster to be at least L and at most U. The set of constraints (5) ensures that the benefit between nodes v_i and v_j is 0 if $\{v_i, v_j\} \notin E$.

The CCP is closely related to three other clustering problems: the graph partitioning problem (GPP) [2–4,15,30], the maximally diverse grouping problem (MDGP) [5,10,14,19,28,29,33], and the handover minimization problem (HMP) [23,26]. First, the GPP is a special case of the CCP when the lower and upper capacity limits of the clusters are respectively set to 0 and $(1 + \epsilon) \lceil \frac{\sum_{i=1}^{n} w_i}{p} \rceil$, where ϵ (\in [0,1)) is a predetermined imbalance parameter. As such, the CCP is also known as the node capacitated graph partitioning problem [11–13,27] or the min-cut clustering problem [20] in the literature. Second, the MDGP is also a special case of the CCP when the given graph is a complete graph and the nodes have a unit weight $(w_i = 1, i = 1, 2, ..., n)$ [23]. Additionally, as discussed in [23,26], the HMP can be viewed as a practical application of the CCP in the context of mobile networks.

Given that the CCP generalizes the NP-hard MDPG, GPP, and HMP problems, the CCP is at least as computationally difficult as these problems. Moreover, any real-world applications that can be formulated by the MDPG, GPP, or HMP models can be cast as the CCP, such as creation of peer review groups [7], parallel computing [18], assignment of students to groups [19], VLSI design [33], etc.

Given the NP-hard nature of the CCP and its practical importance, a large number of studies have been proposed to investigate the problem and the three related clustering problems. Below, we highlight some most recent approaches on the CCP, while refereeing the reader to two recent papers [9,23] for a comprehensive review of existing studies in the literature.

In 2011, Deng and Bard [9] proposed a greedy randomized adaptive search procedure with path relinking (GRASP+PR) by hybridizing a construction procedure of initial solution, a randomized variable neighborhood descent method as well as a path-relinking procedure. The reported computational 45 results showed that the proposed GRASP+PR algorithm outperforms the reference algorithms. In 2013, Morán-Mirabal et al. [26] proposed the following three heuristic algorithms for the HMP problem that is a special case of the CCP: a GRASP method (denoted by GQAP in their paper), an evolutionary path-relinking algorithm combined with GRASP (GevPR-HMP), and a population-based biased random-key genetic algorithm (BRKGA). Their study showed that GevPR-HMP achieved the best performance among the three proposed algorithms. In 2014, Lewis et al. [22] made a comparison between the linear and nonlinear models for the CCP under the framework of exact methods, and showed that the quadratic model generally outperforms its equivalent linear alternatives.

Recently (2015), Martínez-Gavara et al. [23] introduced several heuristic algorithms for the CCP, including a new GRASP method, a tabu search (TS)
method, and a hybrid algorithm combining the proposed GRASP and tabu
search methods (GRASP+TS). The authors also adapted a tabu search algorithm with strategic oscillation (TS_SO) originally designed for the MDGP
to solve the CCP. Their study showed that the proposed GRASP+TS and
TS algorithms significantly outperform their reference algorithms, including
their GRASP method, Deng and Bard's GRASP and TS_SO presented in
[9], as well as the GevPR-HMP algorithm of [26]. Consequently, the TS and
GRASP+TS algorithms proposed in [23] can be considered as the current best
performing approaches for the CCP.

In this paper, we are interested in solving the general CCP problem approximately and propose for this purpose an effective iterated variable neighborhood search algorithm (IVNS). The main contributions of the present work can be highlighted as follows:

The proposed IVNS algorithm introduces an extended variable neighborhood descent (EVND) method to ensure an intensified local optimization. Contrary to the standard variable neighborhood descent (VND) method

- [24], our EVND method focuses on a more balanced exploitation between different neighborhoods, which provides the search with a reinforced diversification effect. Additionally, IVNS integrates two dedicated construction procedures to generate initial solutions and a randomized shake procedure to escape deep local optima (i.e., local optimum solutions which are difficult to attain and difficult to escape for a search algorithm).
- When it is assessed on three sets of 133 benchmark instances of the literature, the proposed IVNS algorithm achieves highly competitive performances both in terms of the solution quality and computational efficiency compared to the state-of-the-art results. On the two sets of 50 standard instances, IVNS outperforms the state-of-the-art CCP algorithms in the literature. Moreover, for the 83 popular benchmark instances of the third set, IVNS improves the best known results (new lower bounds) in 28 cases and matches the best known results for the 55 remaining cases.
- The rest of the paper is organized as follows. In the next Section, our IVNS algorithm and its components are described in detail. Section 3 is dedicated to computational assessments based on the commonly used benchmarks and comparisons with the state-of-the-art algorithms in the literature. In Section 4, several essential components of the proposed algorithm are investigated to shed light on how they affect the performance of the proposed algorithm. Concluding comments are summarized in the last section.

⁹⁶ 2 Iterated Variable Neighborhood Search for the CCP

Variable neighborhood search (VNS) [17,24] has been applied with success to many combinatorial optimization problems (see for instances [1,5,25,31,32]). In this work, we follow the general VNS framework and propose the iterated variable neighborhood search (IVNS) method for the CCP which integrates 100 specially designed components to reach a suitable trade-off between inten-101 sification and diversification of the search process. Specifically, the proposed 102 IVNS algorithm employs a randomized construction procedure to generate the 103 initial solution, a new local optimization approach called the EVND method 104 (extended variable neighborhood descent method) to discover local optima, 105 and a shake procedure to perturb the incumbent solution. The proposed IVNS 106 algorithm also employs a diversification stage to produce transition states be-107 tween high-quality local optimum solutions. 108

Algorithm 1: Main framework of IVNS method for CCP

```
Input: Instance I, parameter \beta_{max}, cutoff time t_{max}, \eta shake strength
   Output: The best solution s^* found during the whole search process
 1 s \leftarrow InitialSolution(I)
                                                                 /* section 2.3 */
 \mathbf{z} \ s \leftarrow EVND(s)
                                                              /* section 2.4.3 */
 s s^b \leftarrow s, s^* \leftarrow s
 4 while Time() < t_{max} do
       \beta \leftarrow 0
        /* Intensified search: iterated local optimization with
       Shake and EVND
                                                                                     */
       while \beta < \beta_{max} \land Time() \leq t_{max} \mathbf{do}
 6
                                      /* perturb s^b before EVND improvement,
           s \leftarrow Shake(s^b, \eta)
 7
           section 2.5 */
           s \leftarrow EVND(s)
                                     /* local improvement, section 2.4.3 */
 8
           if f(s) > f(s^*) then
 9
                                 /* update the best solution ever found */
            s^* \leftarrow s
10
           end
11
           if f(s) > f(s^b) then
12
              s^b \leftarrow s, \beta \leftarrow 0 /* s^b denotes the best solution obtained by
13
              the current inner 'while' loop */
           else
14
            \beta \leftarrow \beta + 1
15
           end
16
17
        /* Diversification: additional Shake to escape deep local
       optima
       s^b \leftarrow Shake(s^b, \eta) /* an additional shake of deep local optimum
18
       s^b before next round of iterated local optimization */
19 end
20 return s^*
```

9 2.1 General Procedure

```
Our IVNS algorithm (Algorithm 1) starts from an initial feasible solution that is generated by a randomized construction procedure (Section 2.3) and is improved by the EVND method (lines 1 and 2, Section 2.4.3). Then it enters a 'while' loop in which an iterated local optimization (the inner 'while' loop, lines 5 to 17) and a diversification phase (the Shake call, line 18) are iteratively performed until a cutoff time t_{max} is reached.

The inner 'while' loop aims to find, from a given solution (a local optimum), an improved local optimum by iterating the Shake procedure (line 7) followed by the EVND procedure (line 8). The starting solution is first shaken by mak-
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ing η changes (η is called shake strength, see Section 2.5) which serves as the starting point of the extended variable neighborhood descent procedure (see 120 Section 2.4.3). The outcome of each EVND application is used to update the 121 best solution ever found (s^* , lines 9-11) and the best local optimum found during the current iterated local optimization phase (s^b , lines 12-16). The counter 123 β indicates the number of consecutive local optimization (Shake+EVND) it-124 erations during which s^b is not updated (β is reset to 0 each time an improved 125 local optimum s^b is discovered). The inner 'while' loop exits when the cuttoff 126 time is reached (in which case the whole algorithm terminates) or when β at-127 tains a fixed value β_{max} (a large β_{max} thus induces a more intensified search). 128 In the later case, s^b indicates a deep local optimum that the inner Shake call (line 7) is not sufficient to help EVND to escape. For this reason, we apply an 130 additional Shake call (line 18) to modify s^b before giving it to the next round 131 of the inner 'while' loop. 132

Note that with the second Shake call (line 18), the next inner 'while' loop starts the local optimization (EVND) with a doubly shaken starting solution, which diversifies the search strongly and helps escape deep local optima. More generally, the second Shake call may be replaced by other diversification techniques like random or customized restarts. In our case, we simply adopt the same Shake procedure used in the iterated local optimization phase. As shown in Section 3, this technique proves to be suitable and effective for the tested benchmarks. We also provide a study in Section 4.3 about the diversification effect of this second Shake application.

2.2 Search Space, Evaluation Function and Solution Representation

For a given CCP instance that is composed of a weighted graph G = (V, E, C, w), the number p of clusters, and the lower and upper limits L and U on the capacity of clusters, the search space Ω explored by the IVNS algorithm contains all feasible solutions, i.e., all partitions of the nodes of V into p clusters such that the weight of each cluster lies between its lower and upper limits.

Formally, let $\pi: V \to \{1, ..., p\}$ be a partition function of the n nodes of V to p clusters. For each cluster $g \in \{1, ..., p\}$, let $\pi_g = \{v \in V : \pi(v) = g\}$ (i.e., π_g is the set of nodes of cluster g). Then the search space Ω explored by our IVNS algorithm is given by:

$$\Omega = \{\pi : \forall g \in \{1, ..., p\}, L \le |\pi_g| \le U, |\pi_g| = \sum_{v \in \pi_g} w(v)\}.$$

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For any candidate partition $s = \{\pi_1, \pi_2, ..., \pi_p\}$ in Ω , its quality is evaluated by the objective function value f(s) of the CCP:

$$f(s) = \sum_{g=1}^{p} \sum_{v_i, v_j \in \pi_g, i < j} c_{ij}$$
 (6)

Given a candidate solution $s = \{\pi_1, \pi_2, ..., \pi_p\}$, IVNS employs a n-dimensional vector x (element coordinate vector) to indicate the cluster of each node (or element). That is, if element i belongs to cluster π_q , then x[i] = g (i \in 157 $\{1,\ldots,n\}$). IVNS additionally uses a p-dimensional vector WC (cluster weight 158 vector) to indicate the weight of each cluster of solution s, i.e., WC[g] = $\sum_{v \in \pi_g} w(v) \ (\forall g \in \{1, \dots, p\}).$ Moreover, to facilitate neighborhood operations 160 during the search process, the algorithm maintains a $n \times p$ matrix γ in which 161 the entry $\gamma[v][g]$ represents the sum of edge weights between the node v and the nodes of cluster g in the candidate solution s, i.e., $\gamma[v][g] = \sum_{u \in \pi_g} c_{vu}$. Consequently, any candidate solution $s \in \Omega$ can be conveniently indicated by the x and WC vectors, the γ matrix and its objective function value f, i.e., s $= \langle x, WC, \gamma, f \rangle$.

7 2.3 Initial Solution

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The proposed IVNS algorithm needs, for each run, an initial solution to start its search. In this work, we devise two randomized construction procedures for this purpose. The first procedure (Algorithm 2) operates in two stages. In the first stage, it iteratively performs a series of insertion operations until all clusters satisfy their lower capacity constraint. Specifically, for each insertion operation, a node v and a cluster g are randomly chosen from the set AN of unassigned nodes and the set AC of clusters whose lower bound constraint is not satisfied, then the node v is assigned to cluster g. In the second stage, the construction procedure performs again a series of insertion operations until all nodes are assigned. Each insertion operation consists of randomly picking an unassigned node v and a cluster g such that $WC[g] + w(v) \leq U$, and then assigning v to g, where WC[g] and w(v) denote respectively the current weight of cluster g and the weight of node v.

However, the preliminary experiments showed that it was often difficult to obtain a feasible solution by the above procedure when the upper capacity limit of clusters is very tight. As a result, we modify slightly the above procedure as follows to obtain a second construction procedure. For each insertion operation, instead of randomly picking a node from the set AN of unassigned nodes, we always choose the node v in AN such that v has the largest weight (break ties at random).

Due to the random choices for insertion operations, the construction procedures are able to generate diversified initial solutions which allow the algorithm

Algorithm 2: Initial Solution Procedure

```
1 Function InitialSolution( )
   Input: Instance I
   Output: A feasible initial solution (denoted by \langle x[1:n], WC[1:p], \gamma, f \rangle)
 2 AN \leftarrow \{1, 2, ..., n\}
                                     /* AN is the set of available nodes */
 3 AC \leftarrow \{1, 2, \dots, p\}
                                 /* AC is the set of available clusters */
 4 for g \leftarrow 1 to p do
   WC[g] \leftarrow 0
 6 end
    /* WC[g] is the weight of cluster g for the current solution st/
    /* x represents the coordinate vector of current solution
   while AC \neq \emptyset do
       v \leftarrow RandomNode(AN)
                                          /* randomly pick a node from AN */
       q \leftarrow RandomCluster(AC) /* randomly pick a cluster from AC */
 9
       x[v] \leftarrow g
10
       WC[g] \leftarrow WC[g] + w[v]
11
       AN \leftarrow AN \setminus \{v\}
12
       if WC[g] \ge L then
13
           AC \leftarrow AC \setminus \{g\}
14
       end
15
16 end
17 AC \leftarrow \{1, 2, \dots, p\}
   while AN \neq \emptyset do
       Flag \leftarrow \mathbf{true}
19
       while Flag do
20
           v \leftarrow RandomNode(AN) /* randomly pick a node from AN */
21
           g \leftarrow RandomCluster(AC) /* randomly pick a cluster from AC
22
           if WC[g] + w[v] \leq U then
23
               Flag \leftarrow \mathbf{false}
24
           end
25
       end
26
       x[v] \leftarrow g
27
       WC[g] \leftarrow WC[g] + w[v]
28
       AN \leftarrow AN \setminus \{v\}
29
30 end
   Compute \gamma and f for x
                                                                /* Section 2.4.2 */
   return \langle x, WC, \gamma, f \rangle
```

to start each run in a different area of the search space.

91 2.4 $Local\ Optimization\ Method$

Our IVNS algorithm employs the EVND method as its local optimization procedure which extends the standard variable neighborhood descent (VND) method. The detail of the EVND method is described in the following subsections.

Our EVND procedure exploits systematically three neighborhoods, i.e., the insertion neighborhood N_1 , the swap neighborhood N_2 , and the 2-1 exchange neighborhood N_3 . Note that although these three neighborhoods have been proposed in previous studies [9,23], they have never been used together like we do in this work.

The insertion neighborhood N_1 is based on the *OneMove* operator. Give a so-202 lution (or a partition) $s = \{\pi_1, \pi_2, \dots, \pi_p\}$ in the search space Ω , the *OneMove* 203 operator transfers a node v of s from its current cluster π_i to another cluster 204 π_j such that $|\pi_i| - w(v) \geq L$ and $|\pi_j| + w(v) \leq U$, where L and U denote 205 respectively the lower and upper limits of capacity of clusters, w(v) represents the weight of node v, and $|\pi_i|$ and $|\pi_i|$ denote respectively the weights of the clusters π_i and π_j in s. Let $\langle v, \pi_i, \pi_j \rangle$ designate such a move and 208 $s \oplus \langle v, \pi_i, \pi_j \rangle$ be the resulting neighboring solution produced by applying 209 the move to s. Then the neighborhood N_1 of s is composed of all possible 210 neighboring solutions that can be obtained by applying the One Move opera-211 tor to s, i.e., 212

$$N_1(s) = \{s \oplus \langle v, \pi_i, \pi_i \rangle : v \in \pi_i, |\pi_i| - w(v) \ge L, |\pi_i| + w(v) \le U, i \ne j\}$$

Clearly, the size of N_1 is bounded by $O(n \times p)$.

The neighborhood N_2 is defined by the SwapMove operator. Given two nodes v and u which are located in two different clusters of s, the SwapMove(v, u) operator exchanges their clusters such that the resulting neighboring solution is still feasible. Thus, the neighborhood N_2 of s is composed of all feasible neighboring solutions that can be obtained by applying SwapMove to s, i.e.,

$$N_2(s) = \{ s \oplus SwapMove(v, u) : v \in \pi_i, u \in \pi_j, L \le \{ |\pi_i| + w(u) - w(v), |\pi_j| + w(v) - w(u) \} \le U, i \ne j \}$$

The size of N_2 is bounded by $O(n^2)$ and is usually larger than that of N_1 .

The neighborhood N_3 is based on the 2-1 exchange operator (Exchange(v, u, z)). Given the current solution $s = \{\pi_1, \pi_2, \dots, \pi_p\}$ and three nodes v, u and z, where v and u are located in the same cluster π_i and z is located in another cluster π_j , Exchange(v, u, z) transfers the nodes v and u from their current cluster π_i to the cluster π_j , and transfers simultaneously the node z from the cluster π_j to the cluster π_i in such a way that the resulting solution is still feasible. For the current solution s, the neighborhood N_3 of s is composed of all feasible neighboring solutions which can be obtained by applying the

Exchange(v, u, z) operator to s:

```
N_3(s) = \{ s \oplus Exchange(v, u, z) : v, u \in \pi_i, z \in \pi_j, L \le \{ |\pi_i| - w(u) - w(v) + w(z), |\pi_j| + w(v) + w(u) - w(z) \} \le U, i \ne j \}
```

Since the Exchange(v, u, z) operator involves three nodes, the size of N_3 is bounded by $O(n^3)$ and is usually much larger than that of N_2 and N_1 .

Additionally, it is worth noticing that these three neighborhoods (i.e., N_1 , N_2 , and N_3) are functionally complementary. Actually, the OneMove, SwapMove, and Exchange(v, u, z) operators transfer at a time 1, 2, and 3 nodes, respectively. As a result, their combined use offers more opportunities for the local search procedure to disvover high-quality solutions.

223 2.4.2 Fast Neighborhood Evaluation Technique

Similar to the previous studies for the MDGP [5,21,28,29,31], our EVND pro-224 cedure employs an incremental evaluation technique to calculate rapidly the 225 move value (i.e., the change of objective value) of each candidate move. As 226 mentioned in Section 2.2, our procedure maintains a $n \times p$ matrix γ in which 227 the entry $\gamma[v][g]$ represents the sum of weights between the node v and the 228 nodes of cluster g for the current solution, i.e., $\gamma[v][g] = \sum_{u \in \pi_a} c_{vu}$. With the 229 help of matrix γ , the evaluation function value f can be calculated as f(s) = $\frac{1}{2}\sum_{i=1}^n \gamma[i][x[i]]$ for an initial candidate solution $s=(x[1],x[2],\ldots,x[n])$. More-231 over, the matrix γ is frequently used in the neighborhood search operations 232 (see Algorithms 4 to 6). 233

Based on the current solution (or partition) $s = \{\pi_1, \pi_2, \dots, \pi_p\}$, if a OneMove operation $\langle v, \pi_i, \pi_j \rangle$ is performed, the move value can be easily determined as $\Delta_f(\langle v, \pi_i, \pi_j \rangle) = \gamma[v][j] - \gamma[v][i]$, and then the matrix γ is accordingly updated. More specifically, the i-th and j-th columns of matrix γ are updated as follows: $\gamma[u][i] = \gamma[u][i] - c_{vu}$, $\gamma[u][j] = \gamma[u][j] + c_{vu}$, $\forall u \in V, u \neq v$, where c_{vu} is the edge weight between the nodes v and v. As such, the evaluation function value v can be rapidly updated as v can be ra

When a SwapMove(v, u) operation is performed, its move value is calculated as $\Delta_f(SwapMove(v, u)) = (\gamma[v][x[u]] - \gamma[v][x[v]]) + (\gamma[u][x[v]] - \gamma[u][x[u]]) - 2c_{vu}$, where x[v] and x[u] are the cluster of nodes v and u in the current solution s. As stated in Section 2.2, $x = (x[1], x[2], \dots, x[n])$ represents the coordinate vector of the incumbent solution s. Since a SwapMove(v, u) operation is composed of two consecutively performed OneMove operations, i.e., $s \oplus SwapMove(v, u) = (s \oplus \langle v, x[v], x[u] \rangle) \oplus \langle u, x[u], x[v] \rangle$, matrix γ is consecutively updated two times according to the OneMove move.

When a Exchange(v, u, z) move is performed, the move value is calculated as

```
\Delta_f(Exchange(v,u,z)) = (\gamma[v][x[z]] - \gamma[v][x[v]]) + (\gamma[u][x[z]] - \gamma[u][x[u]]) + (\gamma[z][x[v]] - \gamma[z][x[z]]) + 2(c_{vu} - c_{vz} - c_{uz}). Since a Exchange(v,u,z) move is composed of three consecutively performed OneMove moves, i.e., s \oplus Exchange(v,u,z) = ((s \oplus < v,x[v],x[z]>) \oplus < u,x[u],x[z]>) \oplus < z,x[z],x[v]>, matrix \gamma is consecutively updated three times according to the OneMove move.

Matrix \gamma is initialized at the beginning of each run of the EVND procedure with a time complexity of O(n^2), and is updated after each move operation in
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59 2.4.3 Extended Variable Neighborhood Descent

O(n) for any considered move operator.

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Algorithm 3: Extended Variable Neighborhood Descent (EVND) for CCP

```
1 Function EVND(s_0)
   Input: Solution s_0
   Output: The local optimum solution s
 s \leftarrow s_0
 з repeat
       repeat
 4
          s \leftarrow LSN_1(s)
                                                                /* Algorithm 4 */
 5
          (Flag, s) \leftarrow LSN_2(s)
                                                                /* Algorithm 5 */
 6
       until Flag = false
 7
       (Flaq, s) \leftarrow LSN_3(s)
                                                                /* Algorithm 6 */
   until Flag = false
  return s
10
```

Let N_k $(k = 1, 2, ..., k_{max})$ be a sequence of neighborhood structures (also called the neighborhood in this Section) with respect to a given optimization problem, the standard variable neighborhood descent (VND) method changes in a deterministic way the current neighborhood in order to find a highquality local optimum solution with respect to all k_{max} neighborhoods [9,24]. Specifically, the standard VND method starts with the first neighborhood N_1 (k=1) and makes a complete exploitation of the neighborhood. Then, the VND method switches orderly to the next neighborhood N_{k+1} $(k \leftarrow k+1)$ when the current neighborhood N_k $(k = 1, 2, ..., k_{max} - 1)$ is fully explored without finding an improving solution. Moreover, the search process switches immediately to the first neighborhood N_1 as soon as an improving solution is detected in the current neighborhood N_k , i.e., $k \leftarrow 1$. Finally, the VND method stops if the search process reaches the last neighborhood $N_{k_{max}}$ and no improving solution can be found in $N_{k_{max}}$, and the best solution found during the search process is returned as the result of the VND method. Clearly, the returned solution is a local optimum solution with respect to all k_{max} neighborhoods.

Algorithm 4: Local search with N_1

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1 Function LSN_1(x, WC, \gamma, f)
   Input: x[1:n], WC[1:p], \gamma, f
   Output: The local optimum solution (denoted by \langle x, WC, \gamma, f \rangle)
    /*\ WC represents the weight vector of clusters
                                                                                               */
    /* x represents the coordinate vector of current solution
                                                                                               */
 2 Improve \leftarrow \mathbf{true}
   while Improve = true do
        Improve \leftarrow \mathbf{false}
 4
        for v \leftarrow 1 to n do
 5
            for q \leftarrow 1 to p do
 6
                if (x[v] \neq g) \land (WC[x[v]] - w[v] \ge L) \land (WC[g] + w[v] \le U) then
 7
                     \Delta_f \leftarrow \gamma[v][g] - \gamma[v][x[v]]
 8
                     if \Delta_f > 0 then
                         WC[x[v]] \leftarrow WC[x[v]] - w[v]
10
                         WC[g] \leftarrow WC[g] + w[v]
11
                         x[v] \leftarrow g
12
                         f \leftarrow f + \Delta_f
13
                                                                      /* Section 2.4.2 */
                         Update matrix \gamma
14
                         Improve \leftarrow \mathbf{true}
15
                     end
16
                end
17
            end
18
        end
19
   end
20
   \mathbf{return} < x, WC, \gamma, f >
```

Our EVND method described in Algorithm 3 extends the standard VND method in the sense that EVND employs a different condition to switch from the current neighborhood N_k (k > 1) to the first neighborhood N_1 . In the standard VND method, the search process switches back to the first neighborhood as soon as an improving solution is found in the current neighborhood N_k (even if more improving solutions can be further found in N_k). However, our EVND method switches to the first neighborhood N_1 when one of the following two conditions is satisfied. First, the solution has been updated (or improved) m ($m \ge 1$, a parameter called 'the depth of improvement in neighborhood search') times with the current neighborhood N_k . Second, the solution has been updated (improved) at least one time with the neighborhood N_k and no improving solution can further be found in the neighborhood N_k . Clearly, the standard VND method is a special case of our EVND method when m = 1. Note that compared to the standard VND method, our EVND method imposes a stronger condition to move back to the first neighborhood.

292 Such an extension for the standard VND method is based on two consid-

Algorithm 5: Local search with N_2

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```
1 Function LSN_2(x, WC, \gamma, f)
   Input: x[1:n], WC[1:p], \gamma, f, m
   Output: The obtained solution (denoted by \langle x, WC, \gamma, f \rangle)
    /* WC represents the weight vector of clusters
                                                                                               */
     /* x represents the coordinate vector of current solution
                                                                                               */
 2 Improve \leftarrow true, Flag \leftarrow false, counter \leftarrow 0
   while Improve = true do
        Improve \leftarrow \mathbf{false}
 4
        for v \leftarrow 1 to n-1 do
 5
            for u \leftarrow v + 1 to n do
 6
                if (x[v] \neq x[u]) \land (L \leq WC[x[v]] + (w[u] - w[v]) \leq U) \land
 7
                 (L \leq WC[x[u]] + (w[v] - w[u]) \leq U) then
                     \overline{\Delta}_f \leftarrow (\gamma[v][x[u]] - \gamma[v][x[v]]) + (\gamma[u][x[v]] - \gamma[u][x[u]]) - 2c_{vu}
 8
                     if \Delta_f > 0 then
 9
                         WC[x[v]] \leftarrow WC[x[v]] + (w[u] - w[v])
10
                         WC[x[u]] \leftarrow WC[x[u]] + (w[v] - w[u])
11
                         Swap(x, v, u)
12
                         f \leftarrow f + \Delta_f
13
                                                                      /* Section 2.4.2 */
                         Update matrix \gamma
14
                         Flag \leftarrow \mathbf{ture}
15
                         Improve \leftarrow \mathbf{true}
16
                         counter \leftarrow counter + 1
17
                         if counter \geq m then
18
                             return \langle Flag, x, WC, \gamma, f \rangle
                                  /* Return the reached solution and stop the
                             function */
                         end
20
                     end
21
22
                end
            end
23
        end
24
25 end
   return \langle Flag, x, WC, \gamma, f \rangle
```

erations. First, in the standard VND method, the first neighborhood N_1 is explored more often than the other neighborhoods since we move back to N_1 as soon as an improving solution is discovered in the current neighborhood N_k (k > 1). However, a more balanced exploitation of all the k neighborhoods constitutes another possibility and may help the search process to discover better solutions. Compared to the standard VND method, our EVND method promotes a more balanced exploitation of the neighborhoods N_k ($k = 2, 3, ..., k_{max}$) relative to the first neighborhood N_1 . Second, the solutions returned by the neighborhoods N_k ($k = 2, 3, ..., k_{max}$) generally have a larger distance from the local optimum solution produced most recently by the first neighborhood N_1 with our EVND method than with the standard VND method. Thus, compared to the standard VND method, our EVND method creates some diversification effect during its intensified descent process with each neighborhood.

Algorithm 6: Local search with N_3

```
1 Function LSN_3(x, WC, \gamma, f)
   Input: x[1:n], WC[1:p], \gamma, f, m
   Output: The obtained solution (denoted by \langle x, WC, \gamma, f \rangle)
    /* WC represents the weight vector of clusters
                                                                                                */
    /* x represents the coordinate vector of current solution
                                                                                                */
 2 Improve \leftarrow true, Flag \leftarrow false, counter \leftarrow 0
   while Improve = true do
        Improve \leftarrow \mathbf{false}
 4
        for v \leftarrow 1 to n-1 do
 5
            for u \leftarrow v + 1 to n do
 6
                for z \leftarrow 1 to n do
 7
                     if (x[v] = x[u] \land x[v] \neq x[z]) \land
 8
                     (L \le WC[x[v]] + (w[z] - w[u] - w[v]) \le U) \land
                     (L \le WC[x[z]] + (w[v] + w[u] - w[z]) \le U) then
                         \overline{\Delta}_f \leftarrow (\gamma[v][x[z]] - \gamma[v][x[v]]) + (\gamma[u][x[z]] - \gamma[u][x[u]]) +
 9
                         (\gamma[z][x[v]] - \gamma[z][x[z]]) + 2(c_{vu} - c_{vz} - c_{uz})
                         if \Delta_f > 0 then
10
                             WC[x[v]] \leftarrow WC[x[v]] + (w[z] - w[u] - w[v]),
11
                             WC[x[z]] \leftarrow WC[x[z]] + (w[v] + w[u] - w[z])
                             swap \leftarrow x[v], x[v] \leftarrow x[z], x[u] \leftarrow x[z], x[z] \leftarrow swap
12
                              f \leftarrow f + \Delta_f
13
                                                                      /* Section 2.4.2 */
                              Update matrix \gamma
14
                              Flag \leftarrow \mathbf{ture}
15
                              Improve \leftarrow \mathbf{true}
16
                             counter \leftarrow counter + 1
17
                             if counter > m then
18
                                  return < Flag, x, WC, \gamma, f >
19
                                        /* Return the reached solution and stop
                                  the function */
                             end
20
21
                         end
                     end
22
                end
23
            end
24
        end
25
26 end
   return \langle Flag, x, WC, \gamma, f \rangle
```

Our EVND method for the CCP exploits three complementary neighborhoods introduced in Section 2.4.1, i.e., N_1 , N_2 and N_3 and is described in Algorithms 309 3 to 6, where the variables x, WC, γ and f have the same meanings as those in Section 2.2.

From Algorithm 3, one can observe that our EVND procedure consists of two loops and each loop stops as long as the corresponding Flag variable receives the value false. Specifically, for the inner loop the Flag variable will get the value false when no improving neighbor exists in the neighborhood N_2 according to Algorithm 5. Similarly, for the outer loop the Flag variable will get the value false when no improving neighbor exists in the neighborhood N_3 according to Algorithm 6. Consequently, the EVND procedure always stops when no improving neighbor exists in the neighborhoods N_2 and N_3 for the incumbent solution.

2.5 Shake Procedure

```
Algorithm 7: Shake procedure

Function Shake(s_0, \eta)

Input: Solution s_0 strength of shake n
```

```
Input: Solution s_0, strength of shake \eta
Output: The perturbed solution s, matrix \gamma, objective value f
2 s \leftarrow s_0
3 for l \leftarrow 1 to \eta do
4 Randomly pick a neighboring solution s' \in N_1(s) \cup N_2(s)
5 s \leftarrow s'
6 end
7 Compute \gamma and f for s
8 return < s, \gamma, f >
```

When our IVNS algorithm reaches a local optimum solution, we apply a Shake procedure to the reached solution to jump out of the local optimum trap. The 322 Shake procedure used by the IVNS algorithm consists of consecutively per-323 forming η randomly selected feasible OneMove or SwapMove moves, where η 324 is a parameter called the shake strength. In other words, from the incumbent 325 solution s_0 , we construct the $N_1(s)$ and $N_2(s)$ neighborhoods which include all (feasible) neighboring solutions of s (see Section 2.4.1) and then pick randomly 327 a solution s' from the union of $N_1(s)$ and $N_2(s)$ to replace s_0 . We repeat this op-328 eration η times. It is clear that a large (respect. small) η value leads to a shaken 329 solution which will be more (respect. less) distant from the input solution. In 330 this work, the value of η is empirically set as $\eta = min\{15, max\{5, 0.02n\}\},\$ 331 where n is the number of nodes in the graph. Note that it is possible to in-332 clude Exchange moves for the Shake operations. Meanwhile, for the reason of simplicity, we only apply OneMove and SwapMove moves, which proves to be sufficient for our purpose of diversification. The pseudo-code of our Shake 335 procedure is given in Algorithm 7.

337 3 Experimental Results and Comparisons

In this section, we assess the performance of the proposed IVNS algorithm by showing computational results on well-known benchmark instances and by making a comparison with the state-of-the-art algorithms in the literature.

$_{\scriptscriptstyle 1}$ 3.1 Benchmark Instances

Our IVNS algorithm was assessed on three sets of 133 benchmark instances commonly used in the literature. These instances are available at http://www.optsicom.es/ccp/, and their details are described as follows.

- RanReal Set (40 instances): This set was originally proposed in [14] for the MDGP and adapted to the CCP in [23] by generating the node weights with a uniform distribution U(0,10). This set is composed of 20 instances with n = 240, p = 12, L = 75, and U = 125, and 20 instances with n = 480, p = 20, L = 100, and U = 150. For all instances of this set, the edge weights c_{ij} are a real number which is uniformly and randomly generated in (0, 100).
- DB Set (10 instances): This set was originally proposed by Deng and Bard [9] for the MDGP in the context of mail delivery, and adapted to the CCP in [23] by generating the node weights with a uniform distribution U(0,10). These 10 instances are characterized by the following features: n = 82, p = 8, L = 25, and U = 75.
- MM Set (83 instances): These 83 synthetic instances were proposed by Morán-Mirabal et al. [26] for the handover minimization problem and were widely used in the literature. These instances have the following characteristics: $n \in \{20, 30, 40, 100, 200, 400\}, p \in \{5, 10, 15, 25, 50\}$, the edge weights c_{ij} are a real number, and the lower and upper capacity limits of clusters respectively are 0 and a real number depending on each instance.

362 3.2 Parameter Settings and Experimental Protocol

Table 1 Settings of parameters

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Parameters	Section	Description	Values
β_{max}	2.1	strength of intensification search	30
m	2.4.3	depth of improvement in neighborhood search	10
η	2.5	strength of shake	$\min\{15, \max\{5, 0.02n\}\}$

In this Section, we show some basic information about our experiments, including the parameter settings of our algorithm, the reference algorithms, the experimental platform, and the termination criterion of algorithms.

First, Table 1 shows the parameter setting of our IVNS algorithm which was achieved by a preliminary experiment. For this preliminary experiment, we used 20 RanReal instances with n=240 which were also used in the sensibility analysis of parameters presented in Section 4.4. The computational results indicated that for m and β_{max} the default settings shown in Table 1 are suitable for the algorithm (see Section 4.4). For η , it involves three variables, so we manually tuned its value based on a principle that the strength of

shake procedure should be proportional to the size of instance but in an appropriate interval. The computational results on the preliminary experiment indicated that the default setting of η in Table 1 is able to reach an acceptable performance of the algorithm.

Second, according to the previous surveys [23,26], the TS [23], GRASP+TS [23], and GevPR-HMP [26] algorithms can be considered as the state-of-theart algorithms for the CCP. Hence, in the present study we use them as the main reference algorithms for our comparative study.

Our IVNS algorithm was programmed in C++. To make a fair compari-381 son with the state-of-the-art algorithms, we also implemented faithfully the 382 GRASP, TS, GRASP+TS algorithms of [23] which are three state-of-the-art 383 algorithms in the literature ¹. For the GRASP, TS, GRASP+TS algorithms, 384 we adopted the best parameter settings identified in the original paper [23]. 385 Moreover, all source codes were compiled using g++ compiler with the '-O3' 386 flag, and the corresponding experiments were carried out on a computing plat-387 form with an Intel E5-2670 processor (2.80 GHz CPU and 2Gb RAM), running 388 Linux. Following the DIMACS machine benchmark procedure, our machine re-389 quires respectively 0.19, 1.17, and 4.54 seconds for the graphs r300.5, r400.5, 390 $r500.5^{2}$. 391

For the GRASP, TS, GRASP+TS, and IVNS algorithms, we used a cutoff time $t_{max} = n$ (in seconds) as the unique stopping criterion where n is the number of nodes of the input graph.

Finally, for the IVNS algorithm, the initial solution was generated by the second initialization procedure for the handover minimization instances due to their tight upper bounds on the capacity of clusters, and by Algorithm 2 for the remaining instances. For GRASP, TS and GRASP+TS, the handover minimization instances are not used in the experiments, since their initial solution procedures can not guarantee to generate a feasible solution for a part of them due to the tight upper bounds on the capacity of clusters.

3.3 Computational Results and Comparison on the general CCP Instances

The first experiment aims to assess the performance of our IVNS algorithm on the first two sets of instances by comparing its results with those of the stateof-the-art algorithms in the literature. In this experiment, all the compared algorithms (GRASP, TS, GRASP+TS and IVNS) were respectively performed

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¹ The source codes of these algorithms will be available at: http://www.info.univ-angers.fr/pub/hao/ccp.html

² dmclique, ftp://dimacs.rutgers.edu/pub/dsj/clique

Table 2 Comparison between the IVNS algorithm and three state-of-the-art algorithms from the literature (i.e., GRASP, TS, GRASP+TS in [25]) on the first two sets (RanReal and DB) of CCP instances in terms of the best and average objective function values over 20 independent runs. The best results among the compared algorithms are indicated in bold.

_			est				vg	
Instance	GRASP	TS	GRASP+T	S IVNS	GRASP	TS	GRSP+TS	IVNS
$Sparse82_01$	1342.17	1336.82	1342.17	1342.17	1342.13	1315.21	1342.17	1342.17
Sparse82_02	1306.64	1303.17	1306.64	1306.64	1305.65	1281.57	1306.16	1306.64
$Sparse82_03$	1353.94	1353.94	1353.94	1353.94	1351.69	1335.89	1353.00	1353.94
$Sparse82_04$	1291.22	1291.22	1291.22	1291.22	1289.15	1276.85	1290.05	1291.22
$Sparse82_05$	1352.35	1352.35	1352.35	1352.35	1352.35	1328.15	1352.35	1352.35
$Sparse82_06$	1354.61	1354.61	1354.61	1354.61	1353.86	1329.86	1354.61	1354.61
$parse82_07$	1266.94	1266.94	1266.94	1266.94	1266.86	1227.01	1266.89	1266.94
$parse82_08$	1393.02	1391.53	1393.02	1393.02	1393.02	1362.54	1393.02	1393.02
$parse82_09$	1294.12	1294.12	1294.12	1294.12	1293.69	1280.97	1293.46	1294.12
Sparse82_10	1356.98	1356.98	1356.98	1356.98	1356.85	1330.79	1356.95	1356.98
RanReal240_01	192320.30	222871.98	223272.87	224893.92	191140.45	221547.29	222268.07	224785.2
RanReal240_02	185612.48	202356.36	202344.44	204608.66	183435.92	200582.86	200356.15	204415.88
RanReal240 03	179316.65	196422.35	196143.12	198885.19	176821.81	194348.91	194783.74	198626.9
RanReal240 04	197342.26	222298.86	223076.30	225627.16	194629.26	220521.18	221165.75	225227.1
RanReal240 05	175967.25	193358.53	194115.62	195440.94	174465.68	191234.34	192076.34	195228.8
RanReal240 06	192789.55	214840.96	215004.12	216736.00	188264.62	212626.52	213259.64	216474.8
RanReal240 07	191714.87	208223.05	208045.67	209273.70	190379.19	205808.95	206092.48	209004.0
RanReal240 08	185930.72	203595.13	203168.62	205246.82	181699.18	201102.55	201519.15	204958.1
RanReal240 09	189573.48	207711.19	207984.26	209059.28	186992.97	206540.74	206788.13	208789.7
RanReal240 10	176327.61	189597.87	190532.75	192977.28	174638.77	187534.34	188379.13	192788.5
RanReal240 11	184198.31	203109.91	203037.25	204722.75	182673.54	201113.86	201701.83	204523.9
RanReal240 12	181337.55	199710.82	199708.68	201052.53	180048.84	198365.85	198389.30	200904.1
RanReal240 13	180865.29	201238.18	200742.90	202335.99	179893.27	199590.02	198727.63	202139.5
tanReal240 14	194009.94	226813.94	226621.92	228844.44	191947.27	225362.61	225721.97	228512.1
RanReal240 15	173114.22	188896.07	188318.39	191170.98	171311.83	187410.50	187299.92	190914.3
RanReal240 16	182348.50	202475.44	202463.27	203999.02	180823.13	199999.63	200722.29	203834.6
RanReal240_17	181270.70	194155.13	193835.64	195242.31	179607.16	191978.36	191908.95	195114.4
_								
RanReal240_18	174650.37	192772.21	193004.84	195069.62	173876.39	190428.51	190979.42	194853.7
RanReal240_19	179859.43	196739.04	196717.17	199200.03	177521.56	194916.62	195053.62	199019.2
RanReal240_20	191936.64	210399.94	210365.38	212264.10	190110.07	208970.68	208887.59	212046.9
RanReal480_01	463538.35	543259.55	544301.19	555057.10	460340.75	539074.11	539550.62	554331.8
RanReal480_02	446829.64	500646.59	502039.41	510418.44	443573.33	495273.27	497700.18	509519.8
RanReal480_03	434854.27	486379.91	487561.06	496641.22	433059.42	482624.38	483908.86	495847.8
RanReal480_04	455470.88	510971.67	513425.37	521984.68	450861.04	504054.37	507123.99	520891.7
RanReal480_05	415295.30	474548.74	473732.77	483228.99	413263.81	466932.68	469914.28	482595.19
RanReal480_06	461624.20	524191.64	524520.14	533762.18	458049.90	519002.55	520607.74	532888.6
RanReal480_07	461236.11	537464.01	537674.45	545157.68	456319.85	530513.86	532199.71	544530.1
RanReal480_08	460756.67	521894.07	523602.31	532308.09	458299.68	515438.23	518685.30	531417.9
RanReal480_09	466977.73	546057.32	546394.74	556478.39	462121.78	540459.20	541615.49	555098.7
RanReal480_10	447088.04	508294.13	508168.74	519456.96	441810.74	503161.12	504750.89	518612.0
RanReal480_11	451321.35	515296.61	515189.66	523450.04	448295.75	510410.05	509657.31	522814.9
RanReal480_12	434343.91	492469.23	493845.25	501596.63	433067.26	487442.12	488699.18	500580.8
RanReal480_13	467130.54	526936.22	524825.92	534638.19	461557.62	519201.37	521740.67	533763.2
${ m RanReal480}_{14}$	428544.75	500100.04	508349.48	513777.84	426455.75	495859.32	499543.12	512975.7
RanReal480_15	446764.19	509377.07	509005.17	516941.11	443810.07	503159.99	503946.63	516017.9
RanReal480_16	465499.89	540493.75	540840.67	549371.23	462345.11	533502.50	535129.37	548276.1
RanReal480_17	460122.80	531353.71	529388.54	537483.76	458004.02	523459.84	524362.15	536655.0
RanReal480_18	456573.73	515692.20	518675.12	525813.39	452767.79	511193.51	512917.14	524650.8
RanReal480_19	454922.45	514503.74	512339.77	522158.86	449744.91	506858.76	508311.67	521180.8
RanReal480 20	443851.41	510045.22	509167.33	518288.03	440398.01	503995.42	505190.58	517261.93
#Best	10	7	10	50	2	0	4	50
p-value	2.54e-10	5.47e-11	2.54e-10		4.26e-12	1.54e-12	1.18e-11	

Table 3 Comparison between the IVNS algorithm and three state-of-the-art algorithms from the literature (i.e., GRASP, TS, GRASP+TS [25]) on the first two sets (RanReal and DB) of CCP instances in terms of the standard deviation and the average running time to reach its final objective value. Each instance was independently solved 20 times by each algorithm respectively.

			eviation (σ)				$ne_{avg}(s)$	ma
nstance	GRASP	TS	GRASP+	TS IVNS	GRASP	TS	GRASP+	TS IVNS
Sparse82_01	0.16	23.24	0.00	0.00	14.01	9.31	15.15	0.13
parse82_02	0.93	19.99	0.97	0.00	30.82	7.53	29.27	0.82
$Sparse82_03$	1.24	14.90	1.63	0.00	41.60	2.38	38.78	0.21
$parse82_04$	1.32	12.97	1.04	0.00	30.60	6.36	36.99	4.27
$parse82_05$	0.00	30.33	0.00	0.00	4.97	8.02	5.11	0.07
$Sparse82_06$	1.39	25.63	0.00	0.00	24.43	4.03	26.04	0.08
$parse82_07$	0.18	22.46	0.10	0.00	32.74	4.75	28.10	0.39
parse82_08	0.00	29.24	0.00	0.00	1.00	9.31	0.74	0.03
$parse82_09$	0.40	13.01	0.22	0.00	28.54	5.67	16.31	0.58
$parse82_10$	0.16	24.48	0.07	0.00	29.41	2.08	37.81	0.59
RanReal240_01	864.05	1098.76	601.21	97.88	166.10	15.24	132.87	147.28
$RanReal240_02$	936.74	1140.64	1886.92	102.77	128.76	17.81	132.97	160.27
RanReal240_03	786.12	1192.60	875.04	170.83	123.40	7.19	125.43	146.88
RanReal240_04	1018.21	1302.30	1060.61	237.09	122.63	13.49	146.27	162.63
RanReal240 05	646.56	1255.73	894.36	91.62	113.10	8.38	129.66	161.77
RanReal240_06	1321.33	1251.75	959.32	169.61	128.25	15.04	139.80	165.88
RanReal240 07	592.59	1696.59	1324.09	120.82	114.48	27.88	143.93	120.41
RanReal240_08	1271.82	1184.11	1096.61	139.71	137.49	19.52	128.97	174.29
RanReal240 09	1127.57	1073.39	873.02	148.77	135.58	27.24	158.97	160.17
RanReal240 10	659.31	1160.27	1080.52	154.18	107.53	7.40	127.40	170.78
RanReal240 11	855.28	1127.48	1041.35	96.57	115.17	36.41	162.40	148.56
RanReal240 12	624.13	1347.08	961.73	126.79	128.65	34.82	151.19	169.33
RanReal240 13	531.24	1095.26	1191.67	155.41	102.67	38.44	131.83	150.75
RanReal240 14	1185.33	1086.76	672.46	170.71	112.17	10.11	124.59	141.27
RanReal240 15	780.67	1026.16	700.91	174.08	120.50	8.78	126.35	144.95
RanReal240 16	645.97	1341.25	1033.99	131.32	97.79	19.38	141.58	147.86
tanReal240 17	679.79	1280.03	936.77	109.08	120.85	25.01	142.44	146.03
RanReal240 18	458.00	1155.66	1050.83	126.17	141.20	7.55	130.71	163.49
RanReal240 19	924.99	1173.30	1357.67	109.79	113.09	8.71	125.27	176.31
RanReal240 20								
_	829.60	908.52	816.33	130.92	99.00	24.49	146.64	149.66
RanReal480_01	1767.54	2915.75	2305.94	415.49	276.78	87.81	270.05	369.26
RanReal480_02	1541.69	3027.29	1982.60	569.71	212.88	50.36	276.25	416.40
RanReal480_03	909.49	2529.01	1999.88	426.86	281.57	55.11	274.68	415.80
RanReal480_04	1426.35	4323.08	2867.38	648.97	230.07	53.23	275.02	380.20
RanReal480_05	1094.52	3383.90	1886.34	497.25	310.87	33.56	271.51	338.96
RanReal480_06	1573.22	3178.92	2393.40	555.89	205.83	58.20	291.32	338.25
RanReal480_07	1926.89	2864.48	2451.06	413.13	198.46	63.44	291.77	388.74
RanReal480_08	1404.82	4291.62	2058.61	555.42	194.59	77.79	291.08	373.48
RanReal480_09	1994.95	3774.05	2163.84	514.64	231.09	78.00	282.38	388.08
RanReal480_10	1667.97	2799.90	2715.16	589.69	296.32	49.75	268.99	403.46
RanReal480_11	1488.69	2771.21	2220.12	402.37	243.62	98.13	277.81	382.52
RanReal480_12	1078.08	3170.40	2713.09	540.16	292.27	80.68	296.84	386.04
$RanReal480_{-}13$	2379.98	3611.97	2431.74	423.89	264.67	66.61	289.75	420.59
$RanReal480_14$	1025.07	2482.93	2984.86	408.22	275.91	41.00	276.64	401.09
RanReal480_15	1358.30	3001.21	3149.15	408.07	241.74	86.60	296.67	375.96
RanReal480_16	1331.41	4488.81	2636.34	590.34	217.53	56.34	279.50	366.12
RanReal480_17	1306.58	3384.98	2538.33	402.38	274.19	56.09	286.52	389.54
RanReal480_18	1343.73	4530.39	2388.17	494.86	248.92	80.52	307.61	379.04
RanReal480_19	2115.36	2949.64	2357.29	550.77	248.76	49.19	282.87	405.61
RanReal480_20	1146.60	3505.30	2635.41	530.58	255.89	91.93	288.15	398.10
±Best	2	0	4	50				
-value	4.26e-12	1.54e-12	1.18e-11					

20 times on each instance, based on the experimental protocol of Section 3.2.
The computational results are summarized in Tables 2 and 3.

In Table 2, the first column identifies the instances, columns 2–4 show respec-409 tively the best objective values (f_{best}) obtained by the three reference algo-410 rithms (GRASP, TS, GRASP+TS), and column 5 reports the best objective 411 values of our IVNS algorithm. Columns 6–9 show respectively the average objective values for the four compared algorithms (f_{avg}) . The best results among 413 the algorithms in terms of the best and average objective values are indicated 414 in bold. In Table 3, columns 2–5 show the standard deviation (σ) of the objec-415 tive values obtained over 20 runs for the compared algorithms, respectively, 416 and columns 6–9 give the average running times (in seconds) of the algo-417 rithms to reach their respective objective values $(time_{avq})$. The row #Best of 418 the tables indicates the number of instances for which the corresponding algorithm produces the best results among the compared algorithms. In addition, 420 to verify whether there exists a significant difference between the reference 421 algorithms and our IVNS algorithm on the best and average objective val-422 ues, as well as the standard deviation of objective values, the p-values from 423 the non-parametric Friedman test are reported in the last row of the tables. 424 Notice that a p-value smaller than 0.05 means that there exists a significant 425 difference between two sets of results compared.

One observes from Tables 2 and 3 that the proposed IVNS algorithm outper-427 forms the reference algorithms. First, IVNS obtained the best result on all 428 50 instances in terms of the best objective value, whereas the GRASP, TS, 429 GRASP+TS algorithms produced respectively the best result on 10, 7 and 430 10 instances. Second, when comparing the average objective values, it can be 431 found that the IVNS algorithm yielded the best result on all instances, whereas 432 the GRASP, TS, and GRASP+TS algorithms respectively obtained the best results on only 2, 0, 4 instances. In addition, the small p-values (< 0.05) confirm the significant differences between the results of IVNS and those of the 435 compared reference algorithms. 436

Finally, compared to the reference algorithms, the IVNS algorithm produced the smallest standard deviation (σ) on all tested instances, indicating that IVNS is the most robust algorithm among the compared algorithms, which is also confirmed by the associated small p-values.

441 3.4 Computational Results and Comparison on the Handover Minimization 442 Instances

The second experiment aims to assess the performance of the IVNS algorithm on the set of 83 handover minimization instances with $n \le 400$, where for each

Table 4
Comparison between the IVNS algorithm and the three reference algorithms in [26] on the set of handover minimization instances. Each instance was independently solved 20 times by the IVNS algorithm, and the current best results are indicated in bold. The results are given in the form of minimization to make a direct comparison with the results from the literature.

Instance	BKS	m the lit	GQAP	BRKGA			IVNS		
		f_{best}	f_{best}	f_{best}	f_{best}	f_{avg}	f_{worst}	σ	$time_{avg}(s$
100_15_270001	19000	19174	19000	19000	19000	19000.00	19000	0.00	1.01
100_15_270002	22686	22686	22686	23288	22686	22686.00	22686	0.00	0.71
100_15_270003	14558	14558	14558	14616	14558	14558.00	14558	0.00	0.09
100 15 270004	19700	19762	19700	19882	19700	19700.00	19700	0.00	0.15
100_15_270005	22746	22892	22746	23092	22746	22746.00	22746	0.00	0.67
100_25_270001	36412	36412	36448	36752	36412	36412.00	36412	0.00	2.42
100 25 270002	38608	39144	38608	39256	38608	38608.00	38608	0.00	1.04
100_25_270003	32686	32966	32686	32708	32686	32686.00	32686	0.00	1.82
100_25_270004	35322	35678	35322	35954	35322	35322.00	35322	0.00	0.26
100 25 270005	36878	36906	36878	37100	36690	36690.00	36690	0.00	0.21
100 50 270001	60922	60922	61172	61554	60922	60922.00	60922	0.00	2.58
100 50 270002	62022	62046	62022	62524	62022	62022.00	62022	0.00	0.53
100 50 270003	54596	54618	54596	55192	54596	54596.00	54596	0.00	4.07
100 50 270004	57894	57894	57894	58208	57894	57894.00	57894	0.00	1.18
100 50 270005	61088	61088	61318	62784	61080	61082.80	61090	4.31	46.02
200 15 270001	81558	81558	82834	81558	81558	81558.00	81558	0.00	12.53
200 15 270002	89810	89810	90620	90506	89492	90502.80	91172	546.53	48.73
200 15 270003	79232	79232	80980	79548	79232	79277.60	80144	198.77	13.39
200 15 270004	78324	78324	80538	80026	78324	78485.50	79726	375.08	52.95
200 15 270005	95998	95998	98826	98830	95680	96137.10	96986	622.92	21.85
200 25 270001	133168	133168	138454	140492	133168	133168.00	133168	0.00	51.17
200 25 270002		136038	140066	140690	133778	133859.80	133926	47.19	68.02
200 25 270003	139438	139438	144120	143724	136782	136795.50	136812	14.92	67.84
200 25 270004	128554	128554	134054	131786	128246	128246.00	128246	0.00	53.92
200 25 270005	148402	148402	154260	152934	147844	147844.00	147844	0.00	10.20
200 50 270001		221550	223096	223098	215388	215531.20	215572	64.28	67.70
200 50 270002	216444	218254	219910	219834	212798	212864.60	212912	36.18	92.01
200 50 270003	221348	221500	222404	221110	214364	214413.90	214426	15.03	61.89
200 50 270004		212044	212544	213170	206476	206509.80	206590	29.01	61.66
200 50 270005		231890	236136	237156	229918	230050.70	230082	22.82	76.55
400 15 270001		372694	456158	375650	369048	372055.40	385786	4442.20	
400 15 270002		370274	460232	383096	365878	369275.90	378508	4126.82	
400 15 270003		358684	448830	366314	352588	356988.80	365886	4140.92	
400 15 270004		334430	406834	346282	331888	339169.90	350388	6361.04	214.63
400 15 270005		361904	457274	377094	360422	363890.10	383154	4970.80	
400 25 270001		570852	663908	579130	545118	546936.70	549318	1026.66	
400 25 270002		544568	658440	554840	528470	529087.80	530118	444.68	201.85
400 25 270003		548000	667982	553162	524678	526220.60	530438	1695.07	
400 25 270004		501750	607672	516416	481568	482070.00	484566	722.65	174.58
400 25 270005		556044	679848	585070	548100	549839.10	557482	2608.26	
400 50 270001		851412	951882	879438	824766	825581.20	826202	402.47	241.94
400 50 270002		845496	949562	874226	823094	824239.00	825442	591.82	216.54
400 50 270003		819242	919140	843242	801586	802672.90	804310	776.71	266.22
400 50 270004		774564	878912	806690	760602	761370.40	763076	553.34	275.49
400 50 270005		854726	940358	882060	828384	829335.50	830116	421.66	238.48
#Improve	0	0	0	0	28				
#Match	17	9	11	2	17				
#Total	45	45	45	45	45				
	-0	20	20		-10				

instance the IVNS algorithm was independently run 20 times. The computational results are summarized in Table 4 for the large instances with $n \geq 100$. For very small instances with $n \leq 40$, the computational results are reported in Appendix (Table 10) since they are very easy to be solved by the IVNS algorithm (see Appendix for the details). Notice that in the present section all results are given in the form of minimization to make a direct comparison between the results of the IVNS algorithm and those reported in the

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literature, and that the results of the maximization form can be converted to the minimization form as follows: $f_{min} = 2(\sum_{i < j} c_{ij} - f_{max})$, where f_{min} and f_{max} respectively correspond to the results of minimization and maximization forms.

Columns 1 and 2 of Table 4 respectively give the instance name and the 456 best known solution (BKS) published in the literature. Columns 3–5 show the 457 best results of three reference algorithms in [26]: a GRASP method (GQAP), 458 a GRASP embedded within a population-based evolutionary path-relinking 459 algorithm (GevPR-HMP), and a population-based biased random-key genetic 460 algorithm (BRKGA). The results of these reference algorithms were directly extracted from [26], which correspond to the best outcomes (f_{best}) yielded by 462 5 runs with a cutoff time of 24 hours based on a cluster running Intel X5650 463 processors at 2.67 GHz or a cluster running Intel Xeon E5530 processors at 464 2.4 GHz [26]. It is worth noting that the cutoff time of the three reference 465 algorithms is much higher than ours (24 hours vs. $n \leq 400$ seconds). Columns 466 6–10 show the results of our IVNS algorithm, including the best objective value 467 (f_{best}) over 20 runs, the average objective value (f_{aqv}) , the worst objective value 468 (f_{worst}) , the standard deviation of objective value (σ) , and the average running 469 time in seconds to reach its final objective value $(time_{avg})$. The rows Improve, 470 Match denote the number of instances for which the associated algorithm 471 improved or matched the best known results in the literature, and row Total 472 shows the total number of instances. Note that the current best results are 473 indicated in bold, and other symbols are the same as those in Table 2. Besides, 474 it should be mentioned that this section focuses on the best results produced by the compared algorithms, since the compared algorithms were run on different 476 computers and the cut-off times of the reference algorithms are much longer 477 than that of our IVNS algorithm. 478

Table 4 clearly discloses that the proposed IVNS algorithm outperforms the 479 three reference algorithms designed for the handover minimization problem. 480 First, the IVNS algorithm improved the best known results for 28 out of 45 481 instances with $n \geq 100$, while matching the best known results for the remain-482 ing instances. Second, compared to any of the three reference algorithms, our 483 IVNS algorithm obtained the better or equal objective values for all instances, 484 even if IVNS uses much shorter cutoff times than that of the reference algo-485 rithms ($n \leq 400$ seconds vs. 24 hours). Third, even the worst objective value 486 produced by the IVNS algorithm is better than the best known result reported 487 in the literature for instances with n = 400, and the average computing time 488 $time_{avg}$ is smaller than 300 for each instance. Finally, one observes that all 489 p-values are smaller than 0.05, implying there exits a significant difference 490 between the results of the IVNS algorithm and those yielded by the reference 491 algorithms. In summary, these outcomes indicate that the proposed IVNS al-492 gorithm is highly efficient for solving the handover minimization instances 493 compared to the state-of-the-art algorithms in the literature [26].

495 4 Analysis and Discussions

We now turn our attention to analyze some essential aspects of the proposed IVNS algorithm, including the local optimization procedure (i.e., the EVND method), the influence of the diversification stage on the performance of IVNS algorithm, and a sensitivity analysis of the key parameters. In this section, all experiments were carried out based on the set of RanReal instances (20 instances with n = 240 and 20 instances with n = 480).

502 4.1 Comparison Between the Standard and Extended VND Methods

The IVNS algorithm employs the extended VND method (EVND) as its local optimization procedure. Since the EVND method is an extension of the standard VND method, we carried out an experiment to compare both methods. In this experiment, both EVND and VND were respectively run 100 times on each instance. Specifically, for each run, both methods were performed with the same initial solution generated by the first construction procedure presented in Section 2.3.

The computational results of this experiment are summarized in Table 5, including the average objective function value (f_{avg}) and the average running time $(time_{avg})$. In addition, the rows Better, Equal and Worse of the table denote the number of instances for which the corresponding algorithm obtained a better, equal, and worse average objective value compared to another one. The p-values from the non-parametric Friedman test are given in the last row of the table.

It can be observed from Table 5 that in terms of the average objective value, the EVND method achieves a better result than the standard VND method for 36 out of 40 instances, whereas both methods consumed a similar computational time for most instances. These outcomes demonstrate the interest of the EVND method compared to the standard VND method.

$_{12}$ 4.2 Importance of 2-1 Exchange Neighborhood N_3

The EVND method employs three complementary neighborhoods i.e., N_1 , N_2 and the 2-1 exchange neighborhood N_3 . While N_1 and N_2 are very popular and their effectiveness has been shown on a number of the clustering problems in the literature [5,6,9,28,29,31], N_3 is not well studied and thus less understood. In this section, we assess the influence of N_3 on the performance of the IVNS algorithm. The computational experiment was carried out as follows.

Table 5 Comparison between the standard VND method and the extended VND (EVND) method on the set of 40 representative instances. Each instance was independently solved 100 times by both algorithms respectively, and better results in the average objective value (f_{avq}) between the compared algorithms are indicated in bold.

Instance	f	ivg	ti	me_{avg}
	VND	EVND	VND	EVND
RanReal240 01	220221.45	221035.18	0.12	0.12
RanReal240 02	199165.17	199461.37	0.09	0.10
RanReal240 03	193878.39	194087.07	0.09	0.10
RanReal240 04	219242.90	220280.46	0.08	0.11
RanReal240 05	190443.88	190569.72	0.08	0.10
RanReal240_06	211538.07	212198.32	0.09	0.10
RanReal240 07	203850.69	204429.68	0.10	0.13
RanReal240_08	200600.21	200710.54	0.13	0.12
RanReal240_09	204291.07	204961.02	0.08	0.10
$RanReal240_10$	186995.53	187202.99	0.09	0.11
RanReal240_11	199062.90	199574.51	0.09	0.11
$RanReal240_12$	196535.07	196618.48	0.08	0.11
$RanReal240_13$	197326.13	197585.12	0.10	0.11
RanReal240_14	224438.53	224784.93	0.12	0.12
RanReal240_15	185489.25	186227.47	0.08	0.10
RanReal240_16	198794.30	199277.26	0.10	0.11
RanReal240_17	189651.07	190188.43	0.07	0.10
$RanReal240_18$	189290.28	189691.65	0.10	0.10
RanReal240 19	193267.47	194274.68	0.08	0.10
RanReal240_20	207193.59	207692.77	0.08	0.10
RanReal480_01	541860.57	545446.40	0.88	0.87
$RanReal480_02$	497118.68	498148.99	1.01	0.95
$RanReal480_03$	483285.49	482184.26	0.99	0.99
RanReal480_04	507951.82	509674.81	0.76	0.90
$RanReal480_05$	469493.30	469172.22	0.86	0.91
RanReal480_06	516732.69	518796.77	0.96	0.95
RanReal480_07	528136.56	533541.23	0.99	0.93
RanReal480_08	516413.17	518435.89	0.81	0.83
RanReal480_09	543150.66	546057.68	0.88	0.98
RanReal480_10	507686.31	508665.48	0.77	0.86
RanReal480_11	511503.09	512682.60	0.96	0.94
RanReal480_12	487411.85	488100.45	1.04	1.08
RanReal480_13	517853.71	521632.82	0.87	0.88
RanReal480_14	500399.35	500139.40	1.01	0.94
$RanReal480_15$	501547.03	503165.49	0.88	0.83
RanReal480_16	536611.41	537921.48	1.00	0.86
RanReal480_17	526315.11	526884.43	0.92	0.95
$RanReal480_18$	508572.09	511441.64	0.88	0.85
RanReal480_19	509748.10	509208.68	0.70	0.84
$RanReal480_20$	502534.92	504453.71	0.93	0.87
#Better	4	36		
$\# ext{Equal}$	0	0		
# Worse	36	4		
$p ext{-}value$		4.20e-7		1.96e-2

We ran our IVNS and IVNS⁻ methods 20 times to solve each instance, where IVNS⁻ is a variant of IVNS in which N_3 (corresponding to subroutine LSN_3 of Algorithm 6) is disabled while keeping the other algorithmic ingredients unchanged. The experimental results are summarized in Table 6, including the average objective value f_{avg} , the standard deviation of objective value (σ) , and the average running time to reach its final objective value $(time_{avg})$, and other symbols are the same as those in the previous tables.

Table 6 shows that without N_3 , the performance of IVNS deteriorates for all instances in terms of average objective value. Moreover, the average computing times indicate that N_3 helps the IVNS algorithm to continue its search for a

Table 6 Comparison between the IVNS method and its a variant (IVNS⁻) in which the neighborhood N_3 is disabled on the set of 40 representative instances. Each instance is respectively solved 20 times by both algorithms, and better results in the average objective value between two algorithms are indicated in bold.

ective value be		argorrinns	are muica	tea in boi		
Instance	f_{ϵ}	ivg		σ	$tim\epsilon$	$e^{2}avg$
	IVNS-	IVNS	IVNS-	IVNS	IVNS-	IVNS
RanReal240 01	223891.05	224785.27	179.47	97.88	114.90	147.28
RanReal240 02	203789.58	204415.88	160.64	102.77	120.46	160.27
RanReal240 03	198236.57	198626.93	96.21	170.83	145.08	146.88
RanReal240 04	224617.33	225227.11	86.58	237.09	149.30	162.63
RanReal240 05	195181.62	195228.86	82.96	91.62	149.44	161.77
RanReal240 06	215491.95	216474.84	126.77	169.61	109.82	165.88
RanReal240 07	208889.10	209004.05	74.03	120.82	147.34	120.41
RanReal240 08	204207.83	204958.19	230.94	139.71	158.62	174.29
RanReal240 09	208562.04	208789.79	50.70	148.77	119.07	160.17
RanReal240 10	192253.79	192788.59	100.09	154.18	147.11	170.78
RanReal240 11	203776.92	204523.95	109.20	96.57	149.70	148.56
RanReal240 12	200251.35	200904.16	145.50	126.79	101.56	169.33
RanReal240 13	201581.76	202139.55	143.75	155.41	123.42	150.75
RanReal240 14	228332.63	228512.11	228.63	170.71	108.74	141.27
RanReal240 15	190130.92	190914.31	190.24	174.08	137.21	144.95
RanReal240 16	203072.49	203834.68	197.23	131.32	110.16	147.86
RanReal240 17	194564.42	195114.49	92.24	109.08	113.22	146.03
RanReal240 18	194370.83	194853.70	121.64	126.17	107.11	163.49
RanReal240 19	198496.90	199019.23	144.56	109.79	111.23	176.31
RanReal240 20	211418.56	212046.92	130.93	130.92	106.77	149.66
RanReal480 01	550160.70	554331.89	777.24	415.49	304.77	369.26
RanReal480 02	507893.39	509519.84	457.07	569.71	286.47	416.40
RanReal480 03	493226.43	495847.80	584.05	426.86	307.52	415.80
RanReal480 04	518088.82	520891.75	462.43	648.97	303.57	380.20
RanReal480 05	481778.58	482595.19	436.13	497.25	310.42	338.96
RanReal480 06	529846.53	532888.64	537.12	555.89	240.48	338.25
RanReal480 07	542575.23	544530.14	675.84	413.13	310.92	388.74
RanReal480 08	529264.25	531417.94	464.02	555.42	265.15	373.48
RanReal480 09	551329.66	555098.72	547.85	514.64	246.68	388.08
RanReal480 10	516929.26	518612.02	466.20	589.69	282.97	403.46
RanReal480 11	520357.01	522814.96	424.04	402.37	318.02	382.52
RanReal480 12	498472.55	500580.84	410.95	540.16	258.80	386.04
RanReal480 13	530678.39	533763.20	628.41	423.89	261.10	420.59
RanReal480 14	509895.03	512975.73	685.12	408.22	251.09	401.09
RanReal480 15	513947.87	516017.98	645.76	408.07	255.18	375.96
RanReal480 16	544921.69	548276.15	933.12	590.34	332.77	366.12
RanReal480 17	533634.44	536655.06	498.31	402.38	277.45	389.54
RanReal480 18	521497.91	524650.86	775.43	494.86	288.94	379.04
RanReal480 19	519184.62	521180.84	716.91	550.77	230.32	405.61
RanReal480 20	514755.82	517261.92	500.77	530.58	286.77	398.10
#Better	0	40				
#Equal	ő	0				
#Worse	40	0				
p-value		2.54e-10				
1						

longer time and thus to attain better solutions. This experiment demonstrates the usefulness of the 2-1 exchange neighborhood for the IVNS algorithm.

4.3 Importance of the Diversification Mechanism

The IVNS algorithm performs an intensified search stage with the iterated local optimization (lines 5–17 of Algorithm 1) and a diversified stage with the Shake procedure (line 18 of Algorithm 1). The diversified stage aims at producing transition states between two high-quality local optima, since these transition states are usually necessary to help the search process to move from

Table 7 Comparative results of the IVNS method with and without its diversified stage (IVNS-D), on the set of 40 representative instances. Each instance was independently solved 20 times by both algorithms respectively, and better results in terms of the average objective value between two algorithms are indicated in bold.

Instance		ivg				$time_{avg}$		
Historice	IVNS-D	IVNS	IVNS-D	IVNS	IVNS-D	IVNS		
RanReal240 01	223986.99	224785.27	272.57	97.88	69.37	147.28		
RanReal240 02	203614.45	204415.88	299.81	102.77	113.36	160.27		
RanReal240 03	197731.77	198626.93	418.98	170.83	100.27	146.88		
RanReal240 04	224424.68	225227.11	459.32	237.09	93.67	162.63		
RanReal240 05	194298.12	195228.86	474.64	91.62	113.46	161.77		
RanReal240 06	215609.74	216474.84	318.55	169.61	90.56	165.88		
RanReal240 07	208341.50	209004.05	378.79	120.82	122.25	120.41		
RanReal240 08	204211.41	204958.19	219.57	139.71	93.92	174.29		
RanReal240 09	208092.99	208789.79	286.18	148.77	109.41	160.17		
RanReal240 10	191828.97	192788.59	482.02	154.18	133.85	170.78		
RanReal240 11	203921.95	204523.95	329.82	96.57	75.89	148.56		
RanReal240 12	199971.56	200904.16	300.91	126.79	105.04	169.33		
RanReal240 13	201224.78	202139.55	467.84	155.41	87.82	150.75		
RanReal240 14	227825.89	228512.11	356.96	170.71	103.34	141.27		
RanReal240 15	189814.49	190914.31	446.62	174.08	81.73	144.95		
RanReal240 16	202951.20	203834.68	412.54	131.32	87.63	147.86		
RanReal240 17	194328.55	195114.49	265.17	109.08	165.12	146.03		
RanReal240 18	193915.24	194853.70	286.06	126.17	104.30	163.49		
RanReal240 19	197900.00	199019.23	461.25	109.79	101.25	176.31		
RanReal240 20	211284.31	212046.92	280.17	130.92	96.18	149.66		
RanReal480 01	552979.67	554331.89	560.30	415.49	375.66	369.26		
RanReal480 02	507974.23	509519.84	816.89	569.71	337.88	416.40		
RanReal480 03	494000.83	495847.80	961.92	426.86	372.23	415.80		
RanReal480 04	519475.06	520891.75	843.47	648.97	367.62	380.20		
RanReal480 05	481098.07	482595.19	832.34	497.25	315.49	338.96		
RanReal480 06	531667.60	532888.64	649.14	555.89	360.97	338.25		
RanReal480 07	543160.19	544530.14	666.03	413.13	345.01	388.74		
RanReal480 08	530127.30	531417.94	626.52	555.42	369.13	373.48		
RanReal480 09	553832.78	555098.72	703.40	514.64	383.55	388.08		
RanReal480 10	516798.04	518612.02	653.19	589.69	327.60	403.46		
RanReal480 11	520835.32	522814.96	952.45	402.37	359.04	382.52		
RanReal480 12	499078.98	500580.84	687.26	540.16	334.42	386.04		
RanReal480 13	532308.08	533763.20	792.43	423.89	390.62	420.59		
RanReal480 14	511808.09	512975.73	635.87	408.22	408.37	401.09		
RanReal480 15	514720.84	516017.98	482.10	408.07	365.89	375.96		
RanReal480 16	547296.05	548276.15	682.57	590.34	371.18	366.12		
RanReal480 17	534975.71	536655.06	719.18	402.38	353.90	389.54		
RanReal480 18	523253.63	524650.86	720.31	494.86	348.96	379.04		
RanReal480 19	519700.55	521180.84	564.17	550.77	378.77	405.61		
RanReal480 20	515947.56	517261.92	567.91	530.58	325.18	398.10		
#Better	0	40	-					
#Equal	0	0						
#Worse	40	0						
p-value		2.54e-10						
p-vaiue		2.54e-10						

a basin of attraction to another basin.

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In order to assess the impact of this diversified stage on the performance of the IVNS algorithm, we created a variant of the IVNS method (denoted by IVNS-D) by removing the Shake operation of line 18 of Algorithm 1 while keeping other components of IVNS unchanged. We ran IVNS-D and IVNS 20 times to solve each instance. The experimental results are summarized in Table 7, where the symbols have the same meanings as those in the previous tables.

Table 7 indicates that IVNS-D deteriorates the results of IVNS. First, IVNS-D performs worse than IVNS on all instances in terms of the average objective

value. Second, concerning the standard deviation (σ) of the objective value, IVNS obtained a better result for all instances. This experiment confirms the usefulness of the additional diversification stage introduced in line 18 of Algorithm 1.

4.4 Sensitivity Analysis of Parameters

Table 8 Sensitivity analysis of the parameter m. Each instance was independently solved 20 times by the IVNS algorithm for each parameter value in the range $\{4, 6, 8, 10, 12, 14, 16, 18\}$, and the average objective values (f_{avg}) over 20 runs are respectively reported.

_				f_a	vg			
$\operatorname{Instance}/m$	4	6	8	10	12	14	16	18
${\rm RanReal240}_01$	224747.89	224743.77	224750.51	224736.19	224734.17	224784.25	224725.39	224718.09
${\rm RanReal240}_02$	204400.52	204403.15	204425.39	204459.24	204400.94	204418.82	204448.37	204449.36
${\rm RanReal240}_03$	198657.99	198717.34	198685.34	198691.63	198679.41	198658.77	198661.33	198685.05
${\rm RanReal240}_04$	225204.66	225140.01	225146.45	225190.13	225152.00	225194.58	225242.84	225239.61
${\rm RanReal240_05}$	195275.00	195287.90	195237.80	195259.40	195256.56	195199.85	195246.73	195246.16
${\rm RanReal240_06}$	216533.35	216475.23	216454.28	216497.78	216513.23	216465.82	216515.60	216491.18
${\rm RanReal240}_07$	209098.93	209062.00	209060.14	209043.44	209092.56	209024.46	209021.64	209029.07
${\rm RanReal240_08}$	204914.37	204947.69	204883.38	204950.99	204938.25	204962.13	204943.61	204930.28
${\rm RanReal240_09}$	208826.26	208832.55	208883.41	208833.99	208799.52	208794.97	208822.74	208745.94
${\tt RanReal240_10}$	192736.25	192755.01	192815.78	192698.13	192811.66	192776.03	192640.29	192796.48
${\rm RanReal240_11}$	204478.83	204444.22	204464.45	204448.14	204470.10	204495.97	204478.49	204454.86
${\rm RanReal240_12}$	200921.94	200878.36	200830.81	200867.36	200808.50	200783.89	200887.89	200824.69
${\rm RanReal240_13}$	202094.54	202050.52	202042.04	202105.03	201987.09	202076.88	202094.15	202098.55
${\rm RanReal240_14}$	228474.87	228487.74	228483.37	228478.88	228531.74	228528.80	228525.70	228557.20
${\rm RanReal240_15}$	190924.82	190924.06	190907.09	190958.90	190939.27	190933.87	190944.36	190913.93
RanReal240_16	203763.28	203789.09	203798.46	203856.97	203816.01	203850.67	203746.08	203801.18
RanReal240_17	195115.48	195125.04	195150.36	195147.21	195078.97	195106.20	195132.90	195141.27
RanReal240_18	194947.69	194852.90	194893.01	194756.48	194875.62	194852.77	194866.09	194836.40
RanReal240_19	198962.52	199040.68	198966.06	198984.75	198934.98	199008.06	198988.46	198974.27
RanReal240_20	212074.56	212092.28	212056.10	212032.47	211998.49	212046.46	212001.59	212105.61
Average	205607.69	205602.48	205596.71	205599.85	205590.95	205598.16	205596.71	205601.96

Table 9 Sensitivity analysis of the parameter β_{max} . Each instance was independently solved 20 times by the IVNS algorithm for each parameter value in the range $\{5, 10, 15, 20, 25, 30, 35, 40\}$, and the average objective values (f_{avg}) over 20 runs are respectively reported.

				f_a	vg			
Instance/ β_{max}	5	10	15	20	25	30	35	40
RanReal240_01	224676.47	224758.30	224738.12	224753.19	224749.78	224769.53	224739.29	224675.94
RanReal240_02	204384.58	204428.48	204454.16	204422.07	204403.51	204425.57	204381.89	204378.07
RanReal240_03	198621.22	198612.88	198694.68	198622.62	198700.29	198600.93	198693.71	198489.30
${\rm RanReal240_04}$	225111.94	225215.51	225217.08	225262.81	225203.17	225225.99	225039.70	225189.87
RanReal240_05	195202.16	195260.55	195222.28	195278.64	195256.13	195158.88	195199.11	195273.42
RanReal240_06	216421.63	216540.77	216524.29	216511.22	216500.76	216531.96	216491.43	216397.47
${\rm RanReal240}_07$	208954.86	209051.89	209053.73	209066.47	209030.62	209042.97	209025.39	208978.27
RanReal240_08	204957.91	204935.06	204950.87	204998.23	204918.30	204968.93	204864.60	204754.79
RanReal240_09	208775.98	208872.97	208803.31	208762.89	208814.66	208793.45	208786.65	208819.28
${\rm RanReal240_10}$	192729.71	192761.86	192767.85	192774.27	192787.08	192666.16	192647.02	192789.16
RanReal240_11	204457.23	204464.00	204483.40	204492.54	204490.35	204487.99	204463.07	204385.61
RanReal240_12	200897.62	200913.55	200930.03	200918.37	200868.58	200824.06	200865.56	200857.78
${\rm RanReal240_13}$	202110.38	202121.17	202114.62	202100.76	202097.89	202124.86	202087.71	202049.26
RanReal240_14	228454.78	228514.51	228484.05	228516.60	228536.93	228490.37	228494.82	228413.24
RanReal240_15	190869.97	190940.52	190895.56	190944.22	190966.06	190940.83	190868.54	190804.69
${\rm RanReal240_16}$	203702.06	203824.85	203821.77	203859.91	203778.12	203774.10	203819.94	203790.17
RanReal240_17	195096.28	195211.71	195161.74	195155.80	195166.45	195159.81	195051.22	194973.69
RanReal240_18	194861.25	194879.05	194882.91	194900.61	194900.42	194861.18	194881.60	194746.11
${\rm RanReal240_19}$	199005.21	199037.12	199047.45	198990.69	198983.59	199071.70	198893.53	198805.32
${\rm RanReal240}_{20}$	211997.53	212060.94	212059.02	212049.21	212060.15	212052.58	211986.43	211926.56
Average	205564.44	205620.28	205615.35	205619.06	205610.64	205598.59	205564.06	205524.90

Our IVNS algorithm employs two main parameters, i.e., m and β_{max} . Pa-

rameter m is employed in the EVND procedure (Section 2.4.3) to control the exploitation balance between the different neighborhoods, a larger value of m leading to a more balanced neighborhood exploitation. Parameter β_{max} is used to control the strength of intensification search, a larger value of β_{max} implying a stronger intensification for the IVNS algorithm. In this section we show a sensitivity analysis of these two key parameters, which also helps to find an appropriate value for each of them.

In this study, we carried out two additional experiments based on 20 RanReal 570 instances with n=240. In the first experiment, we varied the value of m 571 within the range $\{4, 6, 8, 10, 12, 14, 16, 18\}$ and ran the algorithm 20 times for 572 each value of m and each instance, while keeping other parameters with their 573 default values as shown in Table 1. The computational results are summarized 574 in Table 8, where the second row indicates the values of m, the first column 575 gives the names of instances, the other columns show the average objective function values over 20 independent runs (f_{avq}) for each value of m and each 577 instance, and the last row shows the average results over all instances. Simi-578 larly, we varied in the second experiment the value of β_{max} within the range 579 $\{5, 10, 15, 20, 25, 30, 35, 40\}$. The computational results are summarized in Ta-580 ble 9, where the second row gives the values of β_{max} , and the other entries 581 have the same meanings as those in Table 8. 582

First, we observe from Table 8 that the performance of the IVNS algorithm is 583 not sensitive to the setting of parameter m. Specifically, for most instances the 584 different values of m leaded to very similar results in terms of f_{avg} . Indeed, the 585 relative difference between the results yielded by the different parameter values across the 20 instances is very small ($\leq \frac{(205607.69-205590.95)}{205607.69} \times 100\% = 0.0081\%$). 586 587 205607.69 Hence, the default value of m was set to 10 in this work. As for β_{max} , Table 9 588 shows that for most instances the tested values leaded also to similar results in 589 terms of f_{avg} , with a very small relative difference between the results yielded 590 by the different β_{max} values ($\leq \frac{(205620.28-205524.90)}{205620.28} \times 100\% = 0.046\%$). These 591 outcomes indicate that the IVNS algorithm is not sensitive to the setting of parameter β_{max} . Consequently, to ensure that a lasting intensified search effect when a long computational time is allowed, the default value of β_{max} was set 594 to 30 in this study. 595

596 5 Conclusions

The capacitated clustering problem (CCP) is a general and useful model for a number of applications. It also generalizes three well-known NP-hard problems: the maximally diverse grouping problem, the graph partitioning problem, and the handover minimization problem. In this paper, we proposed the iterated variable neighborhood search (IVNS) algorithm for solving the CCP. The proposed algorithm organically combines an extended variable neighborhood descent (EVND) method for intensification and a shake procedure for diversification.

The proposed algorithm was assessed on the 133 instances commonly used in the literature, and the computational results indicated that our IVNS algorithm significantly outperforms the state-of-the-art CCP algorithms both in terms of solution quality and computational efficiency. In particular, the proposed algorithm improved the best known results (new lower bounds) for 28 out of 83 handover minimization instances, while matching the best known results for the 55 remaining instances.

The investigations of several essential components of the proposed algorithm shed light on the following points. First, for the CCP, the EVND method usually outperforms the standard variable neighborhood descent method in terms of the local search ability, and the 2-1 exchange neighborhood N_3 reinforces the intensified search capacity of the EVND method. Second, the diversification stage is essential for the proposed algorithm to reach a suitable trade-off between the diversification and intensification of the search process.

Based on this work, we advance some research perspectives for further im-619 provements. First, within the IVNS algorithm, diversification is ensured by the 620 shake procedure as well as the shake strength. Since different degrees of diver-621 sification may be needed at different search stages, it would be interesting to 622 investigate adaptive techniques able to adjust dynamically the shake strength. 623 Moreover, to escape deep local optima, it would also be useful to study other diversification methods like random or adaptive restarts. Second, using the 625 presented EVND method as a local optimization procedure, it may be possi-626 ble to devise more efficient hybrid evolutionary algorithms for the CCP. Third, 627 the IVNS algorithm only visits feasible solutions. Meanwhile, previous studies 628 like [8,16] showed that tunneling through feasible and infeasible regions can 629 improve the performance of the search process. It would be relevant to study 630 dedicated methods able to explore infeasible regions in a controlled manner. 631 Finally, given that the basic idea of the proposed IVNS algorithm, i.e., in-632 tegrating organically the EVND method with multiple neighborhoods and a 633 diversified shake procedure, is independent of the CCP, it would be interesting 634 to examine its applicability to other grouping or clustering problems. 635

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Table 10 **Appendix**: Computational results of IVNS on the small handover minimization instances. The results are given in the form of minimization to make a direct comparison with the best known results in the literature.

				IVNS		
Instance	BKS	f_{best}	f_{avg}	f_{worst}	σ	$time_{avg}(s)$
20_5_270001	540	540	540.00	540	0.00	0.00
20_5_270002	54	54	54.00	54	0.00	0.00
20_5_270003	816	816	816.00	816	0.00	0.00
20_5_270004	126	126	126.00	126	0.00	0.00
20_5_270005	372	372	372.00	372	0.00	0.00
20_10_270001	2148	2148	2148.00	2148	0.00	0.00
20_10_270002	1426	1426	1426.00	1426	0.00	0.00
20_10_270003	2458	2458	2458.00	2458	0.00	0.00
20_10_270004	1570	1570	1570.00	1570	0.00	0.00
30_5_{270001}	772	772	772.00	772	0.00	0.00
30_5_270002	136	136	136.00	136	0.00	0.00
30_5_270003	920	920	920.00	920	0.00	0.00
30_5_{270004}	52	52	52.00	52	0.00	0.00
30_5_270005	410	410	410.00	410	0.00	0.00
30 10 270001	3276	3276	3276.00	3276	0.00	0.00
30 10 270002	1404	1404	1404.00	1404	0.00	0.00
30 10 270003	2214	2214	2214.00	2214	0.00	0.00
30 10 270004	2150	2150	2150.00	2150	0.00	0.00
30 10 270005	2540	2540	2540.00	2540	0.00	0.00
30 15 270001	6178	6178	6178.00	6178	0.00	0.00
30 15 270002	4042	4042	4042.00	4042	0.00	0.00
30_15_270003	4126	4126	4126.00	4126	0.00	0.00
30 15 270004	3920	3920	3920.00	3920	0.00	0.00
$40_{5}^{2}70001$	610	610	610.00	610	0.00	0.00
40 5 270002	136	136	136.00	136	0.00	0.00
40 5 270003	234	234	234.00	234	0.00	0.00
$40^{-}5^{-}270004$	232	232	232.00	232	0.00	0.02
$40^{-}5^{-}270005$	774	774	774.00	774	0.00	0.00
$40\overline{}1\overline{0}270001$	4544	4544	4544.00	4544	0.00	0.00
40 10 270002	2068	2068	2068.00	2068	0.00	0.00
40 10 270003	2090	2090	2090.00	2090	0.00	0.00
40 10 270004	1650	1650	1650.00	1650	0.00	0.01
$40^{-}10^{-}270005$	4316	4316	4316.00	4316	0.00	0.00
$40^{-}15^{-}270001$	8646	8646	8646.00	8646	0.00	0.01
$40^{-}15^{-}270002$	4586	4586	4586.00	4586	0.00	0.03
$40^{-}15^{-}270003$	5396	5396	5396.00	5396	0.00	0.01
$40^{-}15^{-}270004$	4800	4800	4800.00	4800	0.00	0.00
$40^{-}15^{-}270005$	6272	6272	6272.00	6272	0.00	0.00